

Leica MS60/TS60 User Manual

Nova



Version 1.0
English

- when it has to be **right**

Leica
Geosystems

Introduction

Purchase

Congratulations on the purchase of a MS60/TS60 series instrument.



This manual contains important safety directions as well as instructions for setting up the product and operating it. Refer to "1 Safety Directions" for further information. Read carefully through the User Manual before you switch on the product.

Product Identification

The type and serial number of your product are indicated on the type plate. Always refer to this information when you need to contact your agency or Leica Geosystems authorised service workshop.



Trademarks



- Windows is a registered trademark of Microsoft Corporation in the United States and other countries
 - *Bluetooth*[®] is a registered trademark of Bluetooth SIG, Inc.
 - SD Logo is a trademark of SD-3C, LLC.
- All other trademarks are the property of their respective owners.

Validity of this Manual

This manual applies to all MS60/TS60 instruments. Where there are differences between the various models they are clearly described.

Available Documentation

| Name | Description/Format |  |  |
|-----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|
| MS60/TS60 Quick Guide | Provides an overview of the product together with technical data and safety directions. Intended as a quick reference guide. | ✓ | ✓ |
| MS60/TS60 User Manual | All instructions required in order to operate the product to a basic level are contained in this User Manual. Provides an overview of the system together with technical data and safety directions. | - | ✓ |

| Name | Description/Format |  |  |
|--------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------|
| Captivate Technical Reference Manual | Overall comprehensive guide to the product and application functions. Included are detailed descriptions of special software/hardware settings and software/hardware functions intended for technical specialists. | - | ✓ |

Refer to the following resources for all MS60/TS60 documentation/software:

- the Leica USB documentation card
- <https://myworld.leica-geosystems.com>



Video tutorials are available on:
<http://www.leica-geosystems.com/captivate-howto>

myWorld@Leica Geosystems (<https://myworld.leica-geosystems.com>) offers a wide range of services, information and training material.

With direct access to myWorld, you are able to access all relevant services whenever it is convenient for you, 24 hours a day, 7 days per week. This increases your efficiency and keeps you and your equipment instantly updated with the latest information from Leica Geosystems.

| Service | Description |
|-------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| myProducts | Add all Leica Geosystems products that you and your company own. View detailed information on your products, buy additional options or Customer Care Packages (CCPs), update your products with the latest software and keep up-to-date with the latest documentation. |
| myService | View the service history of your products in Leica Geosystems Service Centres and detailed information on the services performed on your products. For your products that are currently in Leica Geosystems Service Centres view the current service status and the expected end date of service. |
| mySupport | Create new support requests for your products that will be answered by your local Leica Geosystems Support Team. View the complete history of your Support and view detailed information on each request in case you want to refer to previous support requests. |
| myTraining | Enhance your product knowledge with the Leica Geosystems Campus - Information, Knowledge, Training. Study the latest online training material or download training material on your products. Keep up-to-date with the latest News on your products and register for Seminars or Courses in your country. |
| myTrustedServices | Offers increased productivity while at the same time providing maximum security. <ul style="list-style-type: none"> • myExchange With myExchange you can exchange any files/objects from your computer to any of your Leica Exchange Contacts. • mySecurity If your instrument is ever stolen, a locking mechanism is available to ensure that the instrument is disabled and can no longer be used. |

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1 Safety Directions

1.1 General Introduction

Description

The following directions enable the person responsible for the product, and the person who actually uses the equipment, to anticipate and avoid operational hazards.

The person responsible for the product must ensure that all users understand these directions and adhere to them.

About Warning Messages





Warning messages are an essential part of the safety concept of the instrument. They appear wherever hazards or hazardous situations can occur.

Warning messages...

- make the user alert about direct and indirect hazards concerning the use of the product.
- contain general rules of behaviour.

For the users' safety, all safety instructions and safety messages shall be strictly observed and followed! Therefore, the manual must always be available to all persons performing any tasks described herein.

DANGER, WARNING, CAUTION and **NOTICE** are standardized signal words for identifying levels of hazards and risks related to personal injury and property damage. For your safety it is important to read and fully understand the table below with the different signal words and their definitions! Supplementary safety information symbols may be placed within a warning message as well as supplementary text.

| Type | Description |
|----------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  DANGER | Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. |
|  WARNING | Indicates a potentially hazardous situation or an unintended use which, if not avoided, could result in death or serious injury. |
|  CAUTION | Indicates a potentially hazardous situation or an unintended use which, if not avoided, may result in minor or moderate injury. |
| NOTICE | Indicates a potentially hazardous situation or an unintended use which, if not avoided, may result in appreciable material, financial and environmental damage. |
|  | Important paragraphs which must be adhered to in practice as they enable the product to be used in a technically correct and efficient manner. |

1.2 Definition of Use

Intended Use

- Measuring horizontal and vertical angles.
 - Measuring distances.
 - Recording measurements.
 - Capturing and recording images.
 - Automatic target search, recognition and following.
 - Visualising the aiming direction and vertical axis.
 - Remote control of product.
 - Data communication with external appliances.
 - Measuring raw data and computing coordinates using carrier phase and code signal from GNSS satellites.
 - Recording GNSS and point related data.
 - Computing with software.
-

Reasonably Foreseeable Misuse

- Use of the product without instruction.
 - Use outside of the intended use and limits.
 - Disabling safety systems.
 - Removal of hazard notices.
 - Opening the product using tools, for example screwdriver, unless this is permitted for certain functions.
 - Modification or conversion of the product.
 - Use after misappropriation.
 - Use of products with recognisable damages or defects.
 - Use with accessories from other manufacturers without the prior explicit approval of Leica Geosystems.
 - Inadequate safeguards at the working site.
 - Aiming directly into the sun.
-

1.3 Limits of Use

Environment

Suitable for use in an atmosphere appropriate for permanent human habitation: not suitable for use in aggressive or explosive environments.



DANGER

Local safety authorities and safety experts must be contacted before working in hazardous areas, or close to electrical installations or similar situations by the person in charge of the product.

1.4 Responsibilities

Manufacturer of the product

Leica Geosystems AG, CH-9435 Heerbrugg, hereinafter referred to as Leica Geosystems, is responsible for supplying the product, including the user manual and original accessories, in a safe condition.

Person responsible for the product

- The person responsible for the product has the following duties:
- To understand the safety instructions on the product and the instructions in the user manual.
 - To ensure that it is used in accordance with the instructions.
 - To be familiar with local regulations relating to safety and accident prevention.
 - To inform Leica Geosystems immediately if the product and the application becomes unsafe.
 - To ensure that the national laws, regulations and conditions for the operation of e.g. radio transmitters or lasers are respected.
-

1.5

Hazards of Use



CAUTION

Watch out for erroneous measurement results if the product has been dropped or has been misused, modified, stored for long periods or transported.

Precautions:

Periodically carry out test measurements and perform the field adjustments indicated in the user manual, particularly after the product has been subjected to abnormal use and before and after important measurements.



DANGER

Because of the risk of electrocution, it is dangerous to use poles and extensions in the vicinity of electrical installations such as power cables or electrical railways.

Precautions:

Keep at a safe distance from electrical installations. If it is essential to work in this environment, first contact the safety authorities responsible for the electrical installations and follow their instructions.



NOTICE

With the remote control of products, it is possible that extraneous targets will be picked out and measured.

Precautions:

When measuring in remote control mode, always check your results for plausibility.



CAUTION

Be careful when pointing the product towards the sun, because the telescope functions as a magnifying glass and can injure your eyes and/or cause damage inside the product.

Precautions:

Do not point the product directly at the sun.



WARNING

During dynamic applications, for example stakeout procedures there is a danger of accidents occurring if the user does not pay attention to the environmental conditions around, for example obstacles, excavations or traffic.

Precautions:

The person responsible for the product must make all users fully aware of the existing dangers.



WARNING

Inadequate securing of the working site can lead to dangerous situations, for example in traffic, on building sites, and at industrial installations.

Precautions:

Always ensure that the working site is adequately secured. Adhere to the regulations governing safety and accident prevention and road traffic.



CAUTION

If the accessories used with the product are not properly secured and the product is subjected to mechanical shock, for example blows or falling, the product may be damaged or people can sustain injury.

Precautions:

When setting-up the product, make sure that the accessories are correctly adapted, fitted, secured, and locked in position.

Avoid subjecting the product to mechanical stress.

**WARNING**

If the product is used with accessories, for example masts, staffs, poles, you may increase the risk of being struck by lightning.

Precautions:

Do not use the product in a thunderstorm.

**WARNING**

During the transport, shipping or disposal of batteries it is possible for inappropriate mechanical influences to constitute a fire hazard.

Precautions:

Before shipping the product or disposing of it, discharge the batteries by running the product until they are flat.

When transporting or shipping batteries, the person in charge of the product must ensure that the applicable national and international rules and regulations are observed. Before transportation or shipping contact your local passenger or freight transport company.

**WARNING**

High mechanical stress, high ambient temperatures or immersion into fluids can cause leakage, fire or explosions of the batteries.

Precautions:

Protect the batteries from mechanical influences and high ambient temperatures. Do not drop or immerse batteries into fluids.

**WARNING**

If battery terminals are short circuited e.g. by coming in contact with jewellery, keys, metalized paper or other metals, the battery can overheat and cause injury or fire, for example by storing or transporting in pockets.

Precautions:

Make sure that the battery terminals do not come into contact with metallic objects.

**WARNING**

If the product is improperly disposed of, the following can happen:

- If polymer parts are burnt, poisonous gases are produced which may impair health.
- If batteries are damaged or are heated strongly, they can explode and cause poisoning, burning, corrosion or environmental contamination.
- By disposing of the product irresponsibly you may enable unauthorised persons to use it in contravention of the regulations, exposing themselves and third parties to the risk of severe injury and rendering the environment liable to contamination.

Precautions:

The product must not be disposed with household waste.

Dispose of the product appropriately in accordance with the national regulations in force in your country.

Always prevent access to the product by unauthorised personnel.

Product-specific treatment and waste management information can be downloaded from the Leica Geosystems home page at <http://www.leica-geosystems.com/treatment> or received from your Leica Geosystems dealer.

**WARNING**

Only Leica Geosystems authorised service workshops are entitled to repair these products.

1.6



Laser Classification

1.6.1

General

General

The following chapters provide instructions and training information about laser safety according to international standard IEC 60825-1 (2014-05) and technical report IEC TR 60825-14 (2004-02). The information enables the person responsible for the product and the person who actually uses the equipment, to anticipate and avoid operational hazards.

-  According to IEC TR 60825-14 (2004-02), products classified as laser class 1, class 2 and class 3R do not require:
 - laser safety officer involvement,
 - protective clothes and eyewear,
 - special warning signs in the laser working areaif used and operated as defined in this User Manual due to the low eye hazard level.
-  National laws and local regulations could impose more stringent instructions for the safe use of lasers than IEC 60825-1 (2014-05) and IEC TR 60825-14 (2004-02).

1.6.2

Distancer, Measurements with Reflectors

General

The EDM module built into the product produces a visible laser beam which emerges from the telescope objective.

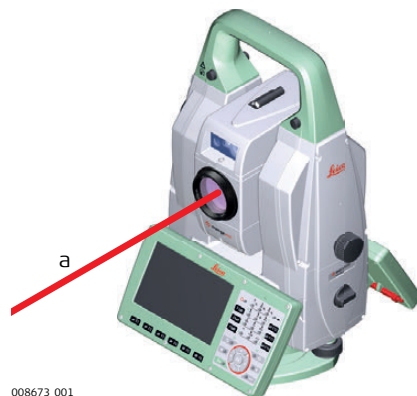
The product described in this section is classified as laser class 1 in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual.

| Description | Value | |
|----------------------------------|-------------------|-------------------|
| | TS60 | MS60 |
| Wavelength | 658 nm | 658 nm |
| Maximum average radiant power | 0.33 mW | 0.33 mW |
| Pulse duration | 800 ps | 700 ps |
| Pulse repetition frequency (PRF) | 100 MHz | 1.1 MHz |
| Beam divergence | 1.5 mrad x 3 mrad | 1.5 mrad x 3 mrad |

Labelling



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a) Laser beam

General

The EDM module built into the product produces a visible laser beam which emerges from the telescope objective.

The laser product described in this section is classified as laser class 3R in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

Direct intrabeam viewing may be hazardous (low eye hazard level), in particular for deliberate ocular exposure. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions. The risk of injury for laser class 3R products is limited because of:

- unintentional exposure would rarely reflect worst case conditions of (e.g.) beam alignment with the pupil, worst case accommodation,
- inherent safety margin in the maximum permissible exposure to laser radiation (MPE)
- natural aversion behaviour for exposure to bright light for the case of visible radiation.

| Description | Value | |
|-----------------------------------------------|---------------------|----------------------------------------------------------|
| | TS60 | MS60 |
| Wavelength | 658 nm | 658 nm |
| Maximum average radiant power | 4.8 mW | 1.7 mW |
| Pulse duration | 800 ps | 1.5 ns |
| Pulse repetition frequency (PRF) | 100 MHz | RL continuous, RL-Scan: 2 MHz RL-Pointer: 4 MHz |
| Beam divergance | 0.2 mrad x 0.3 mrad | 0.2 mrad x 0.3 mrad |
| NOHD (Nominal Ocular Hazard Distance) @ 0.25s | 44 m / 144 ft | 21 m / 69 ft |



CAUTION

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- 1) Prevent direct eye exposure to the beam.
- 2) Do not direct the beam at other people.



CAUTION

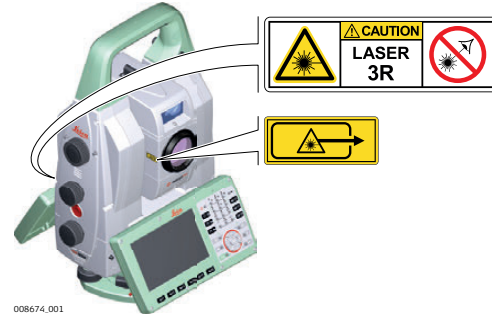
Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

Precautions:

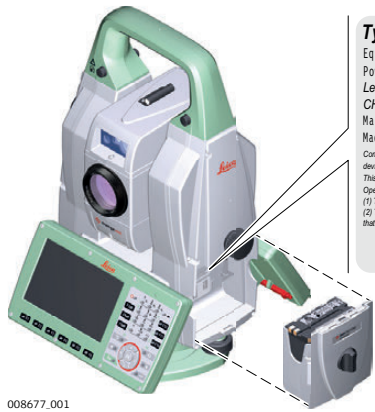
- 1) Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- 2) Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.

Labelling

Laser Radiation
Avoid direct eye exposure
Class 3R Laser Product
according to IEC 60825-1
(2014 - 05)
 $P_{av} = 5.00 \text{ mW}$
 $\lambda = 658 \text{ nm}$
 $t_p = 1500 \text{ ps}$



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Type: MS60 **Art.No.:** 1 2 3 4 5 6
Equip.No.: 1234567 **S.No.:** 1 2 3 4 5 6
Power: 12-18V \approx 40W max
Leica Geosystems AG
CH-9435 Heerbrugg
Manufactured: 20XX
Made in Switzerland

Complies with FDA performance standards for laser products except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.
This device complies with part 15 of the FCC Rules.
Operation is subject to the following two conditions:
(1) This device may not cause harmful interference, and
(2) This device must accept any interference received, including interference that may cause undesired operation.

$P_{av} = 1.8mW$ $\lambda = 658nm$ $t_p = 1500ps$
IEC 60825-1:2014

1.6.4

Red Laser Pointer

General

The laser pointer built into the product produces a visible red laser beam which emerges from the telescope objective.

The laser product described in this section is classified as laser class 3R in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

Direct intrabeam viewing may be hazardous (low eye hazard level), in particular for deliberate ocular exposure. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions. The risk of injury for laser class 3R products is limited because of:

- unintentional exposure would rarely reflect worst case conditions of (e.g.) beam alignment with the pupil, worst case accommodation,
- inherent safety margin in the maximum permissible exposure to laser radiation (MPE)
- natural aversion behaviour for exposure to bright light for the case of visible radiation.

| Description | Value | |
|----------------------------------|---------|----------------------------------|
| | TS60 | MS60 |
| Wavelength | 658 nm | 658 nm |
| Maximum average radiant power | 4.8 mW | 1.7 mW |
| Pulse duration | 800 ps | 1.5 ns |
| Pulse repetition frequency (PRF) | 100 MHz | RL continuous, RL-Scan: 2 MHz |

| Description | Value | |
|-----------------------------------------------|---------------------|---------------------|
| | TS60 | MS60 |
| Beam divergence | 0.2 mrad x 0.3 mrad | 0.2 mrad x 0.3 mrad |
| NOHD (Nominal Ocular Hazard Distance) @ 0.25s | 44 m / 144 ft | 21 m / 69 ft |



CAUTION

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- 1) Prevent direct eye exposure to the beam.
- 2) Do not direct the beam at other people.



CAUTION

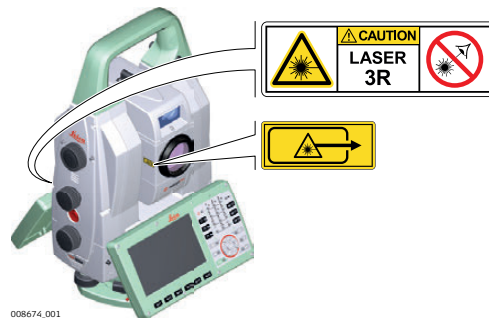
Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

Precautions:

- 1) Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- 2) Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.

Labelling

Laser Radiation
 Avoid direct eye exposure
 Class 3R Laser Product
 according to IEC 60825-1
 (2014 - 05)
 $P_{av} = 5.00 \text{ mW}$
 $\lambda = 658 \text{ nm}$
 $t_p = 1500 \text{ ps}$



1.6.5

Autofocus Capability of Telescope Camera

General

TS60 and MS60 contain a coaxial telescope camera with autofocus capability. When using the auto focus functions a visible laser beam may emerge from the telescope (depending on the focussing mode).

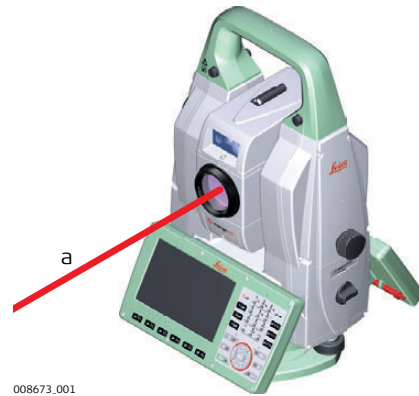
The product described in this section is classified as laser class 1 in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual.

| Description | Value | |
|----------------------------------|---------------------|------------------------------------|
| | TS60 | MS60 |
| Wavelength | 658 nm | 658 nm |
| Maximum average radiant power | 0.37 mW | 0.1 mW |
| Pulse duration | 800 ps | 1.5 ns |
| Pulse repetition frequency (PRF) | 100 MHz | Irregular packages max. 670 kHz |
| Beam divergence | 0.2 mrad x 0.3 mrad | 0.2 mrad x 0.3 mrad |

Labelling



a) Laser beam

1.6.6

Automatic Target Aiming (ATRplus)

General

The Automatic Target Aiming built into the product produces an invisible laser beam which emerges from the telescope objective.

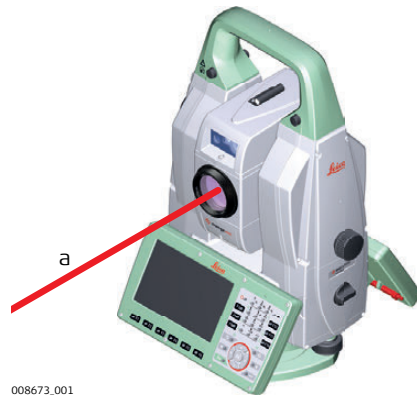
The product described in this section is classified as laser class 1 in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual.

| Description | Value | |
|----------------------------------|---------|---------|
| | TS60 | MS60 |
| Wavelength | 785 nm | 785 nm |
| Maximum average radiant power | 6.2 mW | 6.2 mW |
| Pulse duration | ≤17 ms | ≤17 ms |
| Pulse repetition frequency (PRF) | ≤194 Hz | ≤180 Hz |
| Beam divergance | 25 mrad | 25 mrad |

Labelling



a) Laser beam

General

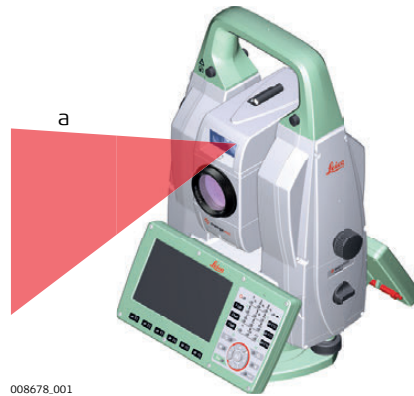
The PowerSearch built into the product produces an invisible laser beam which emerges from the front side of the telescope.

The product described in this section is classified as laser class 1 in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe under reasonably foreseeable conditions of operation and are not harmful to the eyes provided that the products are used and maintained in accordance with this User Manual.

| Description | Value |
|----------------------------------|---------------------|
| Wavelength | 850 nm |
| Maximum average radiant power | 11 mW |
| Pulse duration | 20 ns, 40 ns |
| Pulse repetition frequency (PRF) | 24.4 kHz |
| Beam divergence | 0.4 mrad x 700 mrad |

Labelling

a) Laser beam

1.6.8

Electronic Guide Light EGL



This is only applicable for MS60 and TS60 I.

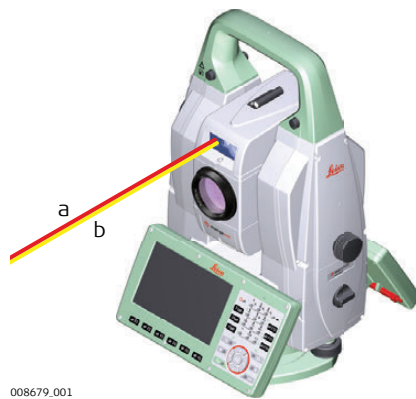
General

The Electronic Guide Light built into the product produces a visible LED beam which emerges from the front side of the telescope.



The product described in this section, is excluded from the scope of IEC 60825-1 (2014-05): "Safety of laser products".

The product described in this section, is classified as exempt group in accordance with IEC 62471 (2006-07) and does not pose any hazard provided that the product is used and maintained in accordance with this user manual.



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- a) LED beam red
- b) LED beam yellow

1.6.9

Laser Plummet

General

The laser plummet built into the product produces a visible red laser beam which emerges from the bottom of the product.

The laser product described in this section is classified as laser class 2 in accordance with:

- IEC 60825-1 (2014-05): "Safety of laser products"

These products are safe for momentary exposures but can be hazardous for deliberate staring into the beam. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions.

| Description | Value |
|----------------------------------|------------|
| Wavelength | 640 nm |
| Maximum average radiant power | 0.95 mW |
| Pulse duration | 10 ms - cw |
| Pulse repetition frequency (PRF) | 1 kHz |
| Beam divergence | < 1.5 mrad |



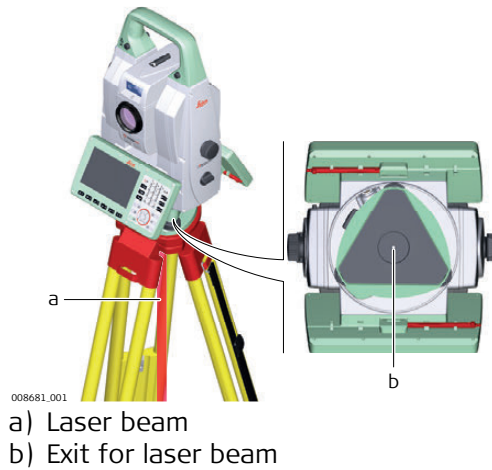
CAUTION

From a safety perspective, class 2 laser products are not inherently safe for the eyes.

Precautions:

- 1) Avoid staring into the beam or viewing it through optical instruments.
- 2) Avoid pointing the beam at other people or at animals.

Labelling



Laser Radiation
Do not stare into the beam
Class 2 Laser Product
according to IEC 60825-1
(2014 - 05)
 $P_{av} = 1.00 \text{ mW}$
 $\lambda = 658 \text{ nm}$

1.7 Electromagnetic Compatibility EMC

Description

The term Electromagnetic Compatibility is taken to mean the capability of the product to function smoothly in an environment where electromagnetic radiation and electrostatic discharges are present, and without causing electromagnetic disturbances to other equipment.



WARNING

Electromagnetic radiation can cause disturbances in other equipment.

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment may be disturbed.



CAUTION

There is a risk that disturbances may be caused in other equipment if the product is used with accessories from other manufacturers, for example field computers, personal computers or other electronic equipment, non-standard cables or external batteries.

Precautions:

Use only the equipment and accessories recommended by Leica Geosystems. When combined with the product, they meet the strict requirements stipulated by the guidelines and standards. When using computers or other electronic equipment, pay attention to the information about electromagnetic compatibility provided by the manufacturer.



CAUTION

Disturbances caused by electromagnetic radiation can result in erroneous measurements.

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that the product may be disturbed by intense electromagnetic radiation, for example, near radio transmitters, two-way radios or diesel generators.

Precautions:

Check the plausibility of results obtained under these conditions.

**CAUTION**

If the product is operated with connecting cables attached at only one of their two ends, for example external supply cables, interface cables, the permitted level of electromagnetic radiation may be exceeded and the correct functioning of other products may be impaired.

Precautions:

While the product is in use, connecting cables, for example product to external battery, product to computer, must be connected at both ends.

Radios or Digital Cellular Phones**WARNING**

Use of product with radio or digital cellular phone devices:

Electromagnetic fields can cause disturbances in other equipment, in installations, in medical devices, for example pacemakers or hearing aids and in aircraft. It can also affect humans and animals.

Precautions:

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment can be disturbed or that humans or animals can be affected.

- Do not operate the product with radio or digital cellular phone devices in the vicinity of filling stations or chemical installations, or in other areas where an explosion hazard exists.
- Do not operate the product with radio or digital cellular phone devices near to medical equipment.
- Do not operate the product with radio or digital cellular phone devices in aircraft.

1.8**FCC Statement, Applicable in U.S.**

The greyed paragraph below is only applicable for products without radio.

**WARNING**

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC rules.

These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

**WARNING**

Changes or modifications not expressly approved by Leica Geosystems for compliance could void the user's authority to operate the equipment.

Labelling MS60/TS60



008677.001

Type: MS60
Equip.No.: 1234567
Power: 12-18V \approx 40W max
Leica Geosystems AG
CH-9435 Heerbrugg
Manufactured: 20XX
Made in Switzerland

Art.No.: 1 2 3 4 5 6
S.No.: 1 2 3 4 5 6

Complies with FDA performance standards for laser products except for deviations pursuant to Laser Notice No. 50 dated June 24, 2007.
 This device complies with part 15 of the FCC Rules.
 Operation is subject to the following two conditions:
 (1) This device may not cause harmful interference, and
 (2) This device must accept any interference received, including interference that may cause undesired operation.

Pav = 1.8mW A = 658nm tp = 1500ps
 IEC 60825-1:2014

Labelling GS14



008606.001

CE 0681

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Type: GS14
Equip. No.: 12345678
Leica Geosystems AG, CH-9435 Heerbrugg
Manufactured: 20XX, Made in Switzerland
Power: 12V nominal / 200 mA max.
Bluetooth QD ID: B015912
Contains FCC ID / IC ID: QIPBGS2 / 7830A-BGS2

Art.No.: 123456
S.No.: 1234567

Labelling GS15



008607.001

Type: GS15
Equip.No.: 1234567
Power: 12V nominal / 0.5 A max.

Leica Geosystems AG
CH-9435 Heerbrugg
Manufactured: 20XX
Made in Switzerland

S.No.: 1234567
Art.No.: 7XXXXX

IC: 6950A-31308
Contains transmitter module:
FCC-ID: 0231308
Bluetooth QD ID: B015912

CE 0681

This device complies with part 15 of the FCC Rules.
 Operation is subject to the following two conditions:
 (1) This device may not cause harmful interference, and
 (2) This device must accept any interference received, including interference that may cause undesired operation.

2022WW105669723

FCC Labelling GEB242



008682.001

Type: GEB242 **Art.No.:** 793975
Li-Ion Battery: 14.8V \approx /5.8Ah
 \approx 15A \approx 5A / 130°C 85.8Wh
Leica Geosystems AG, CH-9435 Heerbrugg
S.No.: 10142
Made in China

CE

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

FCC US
 11WE
 MH29443

Labelling Internal Battery GEB212, GEB222



008611.001



008610.001

Type: GEB212 Art.No.: 772806
 Li-Ion Battery: 7.4V \approx /2.6Ah
 \approx 10A \approx 5A/130°C 19Wh
 Leica Geosystems AG, CH-9435 Heerbrugg
 Manufactured: 20XX S.No.: 0118 Made in China

Type: GEB222 Art.No.: 793973
 Li-Ion Battery: 7.4V \approx /6.0Ah
 \approx 15A \approx 5A/130°C 44.4Wh
 Leica Geosystems AG, CH-9435 Heerbrugg
 S.No.: 10142 Made in China

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CE **UL** **US LISTED**
 ITE Accessory
 E179078, 70YL

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CE **FCC** **US**
 11V
 MH29443

Labelling RadioHandle

RH16



008612.001

RH17



008613.001

Type: RH16
 Art.No.: 777812
 Power: 7.4V/12.5V= \approx /0.2A max.
 Leica Geosystems AG
 CH-9435 Heerbrugg
 Manufactured: 20xx
 Made In Switzerland
 Contains
 Transmitter Module:
 FCC ID: HSW-2400M
 IC: 4492A-2450
 S.No.: 1234567

Type: RH17
 Art.No.: 818467
 Power: 7.4V/12.5V= \approx /0.2A max.
 Leica Geosystems AG
 CH-9435 Heerbrugg
 Manufactured: 20xx
 Made in Switzerland
 Contains
 Transmitter Module:
 FCC ID: PVH0946
 IC: 5325A-0946
 S.No.: 1234567

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CE **UL** **US LISTED**
 ITE Accessory
 E179078, 70YL

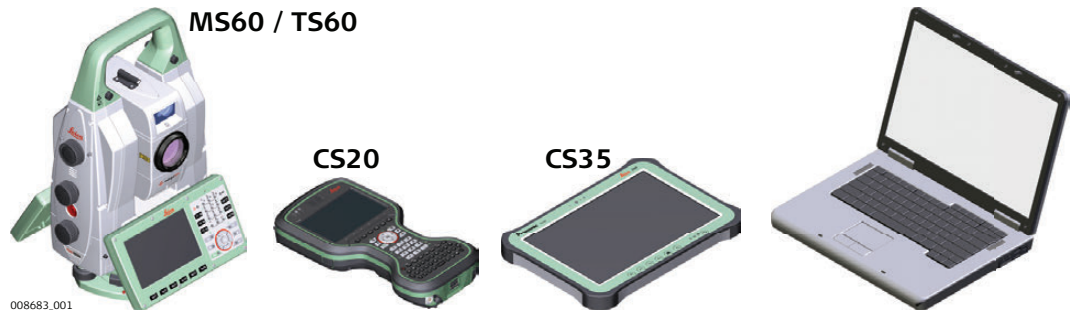
This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CE **FCC** **US**
 11V
 MH29443

2 Description of the System

2.1 System Components

Main Components



| Component | Description |
|-----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MS60/TS60 | <ul style="list-style-type: none"> • an instrument for measuring, calculating and capturing data. • comprised of various models with a range of accuracy classes. • integrated with an add-on GNSS system to form Smart-Station. • combined with a CS20 field controller to conduct remote control surveys. • connected with Infinity to view, exchange and manage data. |
| CS20 field controller | A multi-purpose field controller allowing the remote control of MS60/TS60. |
| CS35 tablet | A tablet allowing the remote control of MS60/TS60. |
| Infinity | An office software consisting of a suite of standard and extended programs for the viewing, exchange and management of data. |

Terms and Abbreviations

The following terms and abbreviations can be found in this manual:

| Term | Description |
|-------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Remote Mode | The instrument is remote controlled by the field controller or tablet using radio. |
| EDM | <p>Electronic Distance Measurement</p> <p>EDM refers to the laser distancer incorporated into the instrument which enables distance measurement.</p> <p>Two measuring modes are available:</p> <ul style="list-style-type: none"> • Prism mode. This mode refers to the ability to measure distances to prisms. On the TS60, it incorporates the long range mode to measure extended distances to prisms. On the MS60, the standard mode (Once) is used for the whole distance range including extended distance prisms. • Any surface mode. This mode refers to the ability to measure distances without prisms. |
| PinPoint | PinPoint refers to the Reflectorless EDM technology which enables an increased measuring range with a smaller laser spot size. Two options are available: R1000 and R2000. |

| Term | Description |
|--------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| EGL | Electronic Guide Light An EGL fitted to an instrument assists with prism targeting. It consists of two differently coloured flashing lights located in the instrument telescope housing. The person holding the prism can align themselves into the line-of-sight of the instrument. |
| ATRplus | Automatic Target Aiming ATRplus refers to the instrument sensor which enables the automatic aiming and locking. |
| Autofocus | Instruments equipped with autofocus offer an automatic focussing of the telescope optics. |
| Automated | Instruments fitted with ATRplus are referred to as Automated. ATRplus refers to the instrument sensor which enables the automatic target aiming to a prism. Three automation modes are available with ATRplus: <ul style="list-style-type: none"> • Manual: no automation and no lock. • Automatic: automatic target aiming to a prism. • LOCK: an already targeted prism is followed automatically. |
| Telescope camera | The camera is coaxially located in the instruments telescope using the 30x magnification of the telescope optics. |
| Overview camera | The overview camera is located in the upper part of the telescope housing and has a fixed focus. |
| PowerSearch | PowerSearch refers to the instrument sensor which enables the automatic rapid finding of a prism. |
| SmartStation | A Leica Nova TS instrument integrated with an add-on GNSS system, comprising hardware and software components, forms a SmartStation. Components of a SmartStation include a SmartAntenna and a SmartAntenna Adapter. A SmartStation provides an additional instrument setup method for determining instrument station coordinates. The GNSS principles and functionality of a SmartStation derive from the principles and functionality of Leica Viva GNSS instruments. |
| SmartAntenna | SmartAntenna with integrated Bluetooth is a component of a SmartStation. It can also be used independently on a pole with a CS20 field controller. Models compatible with a MS60/TS60 instrument are GS14/GS15. Where there are differences between the various models they are clearly described. |
| RadioHandle | A component of remote mode is the RH16/RH17 RadioHandle. It is an instrument carry handle with an integrated radio modem with attached antenna. |
| Communication side cover | Communication side cover with integrated Bluetooth, SD card slot, USB port, WLAN and RadioHandle hotshoe is standard for a MS60/TS60 instrument and a component of a SmartStation. In combination with the RH16/RH17 RadioHandle, it is also a component of remote mode. |

Instrument Models

| Model | TS60 I R1000 | MS60 R2000 |
|--------------------------------------------------------------------------------|-----------------|---------------|
| Angle measurement | ✓ | ✓ |
| Distance measurement to prism | ✓ | ✓ |
| Distance measurement to any surface (reflectorless) | ✓ | ✓ |
| Motorised | ✓ | ✓ |
| Automatic Target Aiming | ✓ | ✓ |
| Lock | ✓ | ✓ |
| PowerSearch (PS) | ✓ | ✓ |
| Overview camera | ✓ | ✓ |
| Telescope camera | ✓ | ✓ |
| Scanning | - | ✓ |
| RS232 and USB interface | ✓ | ✓ |
| SD card and USB stick as storage device | ✓ | ✓ |
| Bluetooth | ✓ | ✓ |
| WLAN | ✓ | ✓ |
| Internal Flash Memory (2 GB) | ✓ | ✓ |
| Hotshoe interface for RadioHandle | ✓ | ✓ |
| Guide Light (EGL) | ✓ | ✓ |
| Autofocus | ✓ | ✓ |
| Uninterruptible electronic power supply due to internal charging functionality | ✓ | ✓ |

2.2

System Concept

2.2.1

Software Concept

Description


All instruments use the same software concept.

Software for TS Models

| Software type | Description |
|-----------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| TS firmware (TS_xxMS60Leica Captive.fw) | <p>The Leica Captivate software is running on the TS instrument and covers all functions of the instrument.</p> <p>The main applications and languages are integrated into the firmware and cannot be deleted.</p> <p>The languages released with Leica Captivate are included in the firmware file.</p> |
| Applications (xx.axx) | <p>Many optional survey-specific applications are available for the TS instruments. All applications are included in the Leica Captivate firmware file and can be loaded separately.</p> <p>Some of the applications are activated freely and require no licence key; others require purchasing and are only activated with a licence key.</p> <p>If the licence is not loaded to the instrument, applications requiring a licence key run for a 40 h trial period. For a trial run, the Measure&Stakeout licence must be available on the TS.</p> |

| Software type | Description |
|----------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Customised applications (xx.axx) | Customised software, specific to user requirements, can be developed using the GeoC++ development kit. Information on the GeoC++ development environment is available on request from a Leica Geosystems representative. |

Software Upload

 Uploading software can take some time. Ensure that the battery is at least 75% full before you start the upload. Do not remove the battery during the upload process.

Software update instructions for all TS models:

- 1) Download the most recent firmware file from <https://myworld.leica-geosystems.com>. Refer to "Introduction".
- 2) Copy the firmware file into the **System** folder on the Leica SD card.
- 3) Start the instrument. Select **Settings\Tools\Update software**. Select the firmware file and start the update.
- 4) When the update is complete, a message appears.

2.2.2

Power Concept

General

Use the batteries, chargers and accessories recommended by Leica Geosystems to ensure the correct functionality of the instrument.

Power Options

| Model | Power supply |
|----------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| All instrument types | Internally by GEB242 battery, OR Externally by GEV219 cable and GEB371 battery. If an external power supply is connected and the internal battery is inserted, then the external power is used for the standard setting. It is possible to configure the main power source to either internal battery or external power supply. If both power sources are available the internal battery serves as an uninterruptible electronic power supply due to internal charging functionality of the internal battery. |
| SmartAntenna | Internally via GEB212 battery fitted into the antenna. |

2.2.3

Data Storage Concept

Description


Data is stored on a memory device. The memory device can be an SD card or internal memory. For data transfer an USB stick can also be used.

Memory Device

SD card: All instruments have an SD card slot fitted as standard. An SD card can be inserted and removed. Available capacity: 1 GB and 8 GB.

USB stick: All instruments have a USB port fitted as standard.

Internal memory: All instruments have an internal memory fitted as standard. Available capacity: 2 GB.

 While other SD cards can be used, Leica Geosystems recommends to only use Leica SD cards and is not responsible for data loss or any other error that can occur while using a non-Leica card.



Unplugging connecting cables or removing the SD card or USB stick during the measurement can cause loss of data. Only remove the SD card or USB stick or unplug connecting cables when the TS instrument is switched off.

Transfer Data

Data can be transferred in various ways. Refer to "4.8 Connecting to a Personal Computer".

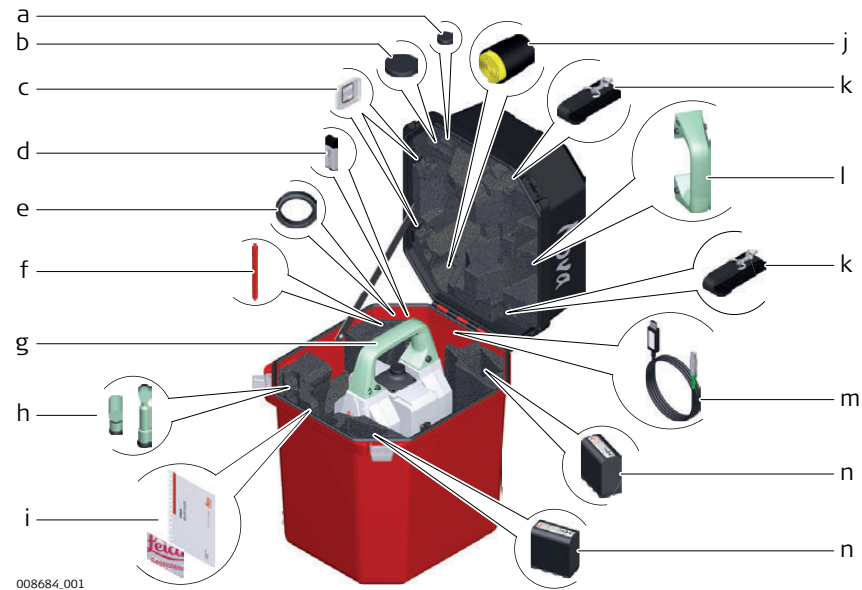


SD cards can directly be used in an OMNI drive as supplied by Leica Geosystems. Other PC card drives can require an adaptor.

2.3

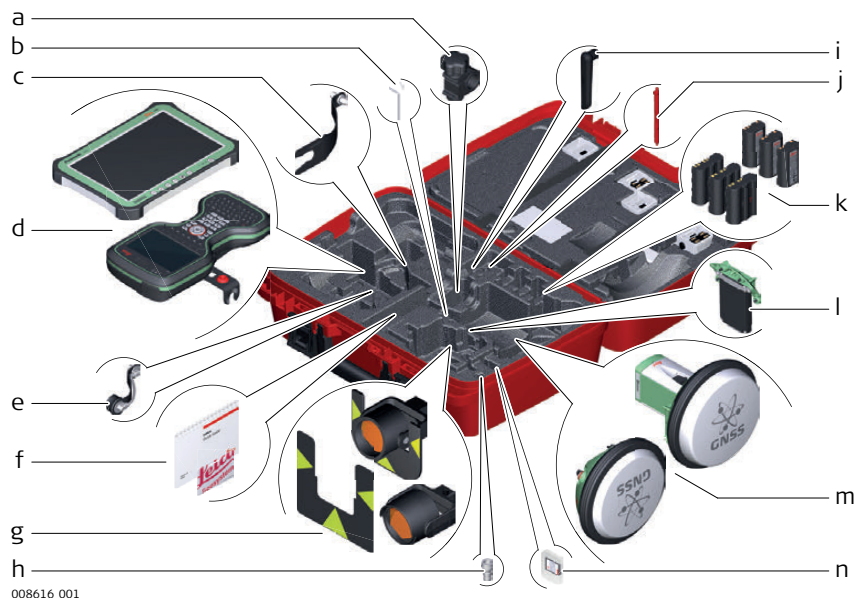
Container Contents

Container for MS60/TS60 and Accessories



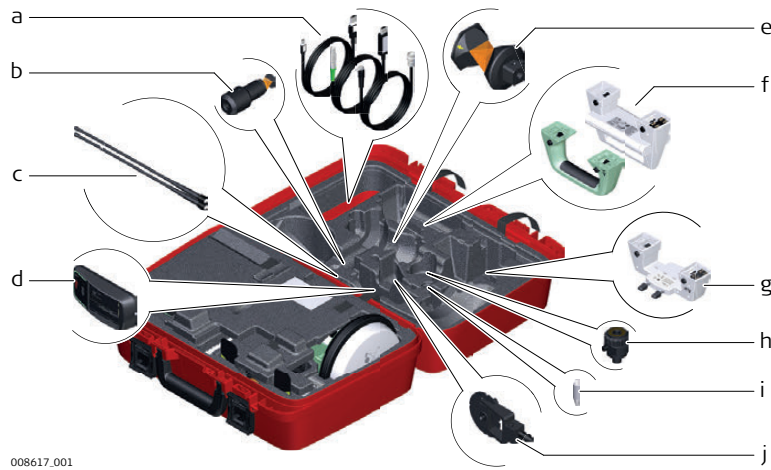
- a) Cover for eyepiece
- b) Cover for objective
- c) SD card and cover
- d) MS1 industrial 1 GB USB memory stick
- e) Counterweight for diagonal eyepiece
- f) Stylus
- g) Instrument with tribrach and standard handle or RadioHandle
- h) GFZ3 or GOK6 diagonal eyepiece
- i) Manuals and USB documentation card
- j) Protective cover for instrument, sunshade for objective lens and cleaning cloth
- k) Container straps
- l) Room for standard handle
- m) GEV234 Data transfer cable
- n) GEB242 battery

**Container for
GS14/GS15 Smart-
Pole/SmartStation
and Accessories -
Part 1 of 2**



- a) GHT63 pole holder clamp
- b) Allen key and adjustment tool
- c) GAD33 antenna arm
- d) CS35 tablet and/or CS20 field controller with GHT66 holder
- e) GAD108 antenna arm
- f) Manuals and USB documentation card
- g) GPR121 circular prism PRO or GZT4 target plate for GPH1 and GPH1 prism holder with GPR1 circular prism
- h) GAD109 QN-TNC Adapter
- i) GAT25 radio antenna
- j) Stylus
- k) GEB212 or GEB331 batteries
- l) SLXX RTK modem
- m) GS14 or GS15 antenna
- n) SD card and cover

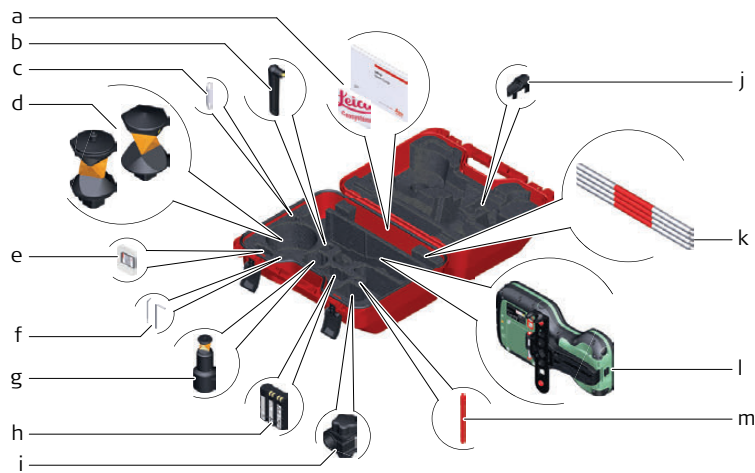
**Container for
GS14/GS15 Smart-
Pole/SmartStation
and Accessories -
Part 2 of 2**



008617.001

- a) Cables
- b) GRZ101 mini prism and GAD103 adapter
- c) GAT_1 or GAT_2 radio antennas
- d) GKL311 charger
- e) GRZ4 or GRZ122 prism
- f) Standard handle or RadioHandle
- g) GAD110 adapter for GS14 and GS15 antenna
- h) GAD31 screw to stub adapter
- i) Mini prism spike
- j) GMP101 mini prism

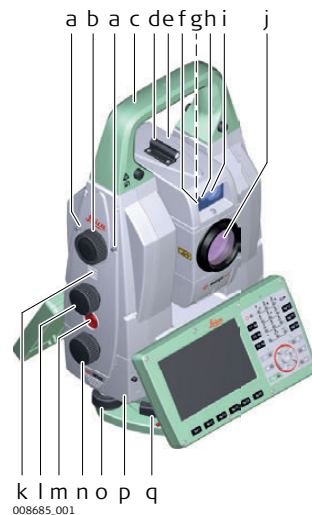
**Container for TS
Robotic Pole Setup,
Small Size**



008620.001

- a) Manuals and USB documentation card
- b) GAT25 radio antenna
- c) Mini prism spike
- d) GRZ4 or GRZ122 prism
- e) SD card and cover
- f) Adjustment tool and allen key
- g) GRZ101 mini prism and GAD103 adapter
- h) GEB331 battery
- i) GHT63 pole holder clamp
- j) Tip for mini pole
- k) GLI115 clip-on bubble for GLS115 mini prism pole
- l) CS20 field controller and GHT66 holder
- m) Stylus

Instrument Components Part 1 of 2



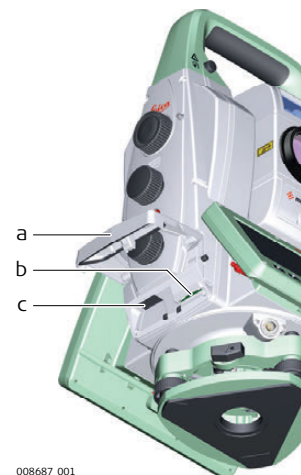
- a) Autofocus button
- b) Servofocus drive
- c) Carry handle
- d) Optical sight
- e) Telescope with EDM, ATRplus, camera sensors, EGL and PS.
- f) EGL
- g) Overview camera
- h) PowerSearch, transmitter
- i) PowerSearch, receiver
- j) Coaxial optics for angle and distance measurements, telescope camera and exit port for visible laser beam for distance measurement
- k) Loudspeaker
- l) Vertical drive
- m) User defined SmartKey
- n) Horizontal drive
- o) Tribrach footscrew
- p) SD card and USB stick compartment
- q) Tribrach securing screw

Instrument Components part 2 of 2



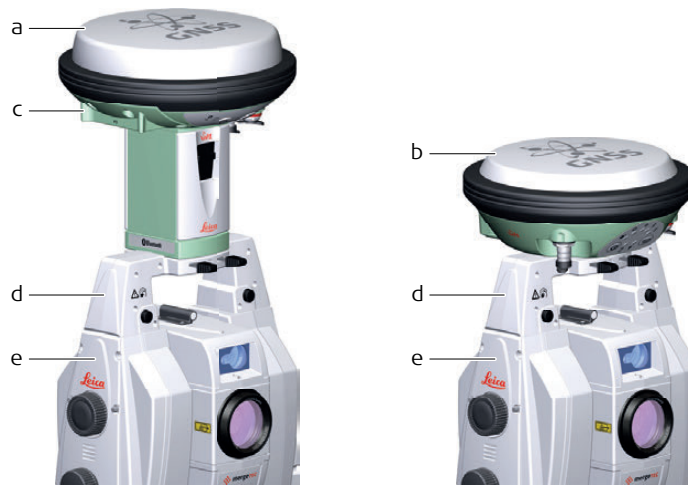
- a) Interchangeable eyepiece
- b) Circular level
- c) Stylus for touch screen
- d) Battery compartment
- e) Vertical drive
- f) Touch screen
- g) Keyboard

Communication Side Cover



- a) Compartment lid
- b) SD card port
- c) USB host port for USB stick

Instrument Components for SmartStation



008688.001

- a) GS15 SmartAntenna
- b) GS14 SmartAntenna
- c) RTK slot-in device
- d) GAD110 SmartAntenna Adapter
- e) Communication side cover

Instrument Components for Remote Mode



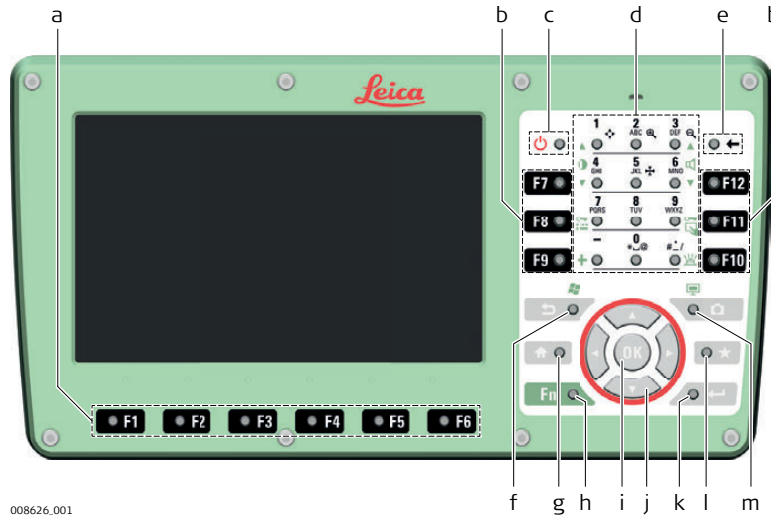
008689.001

- a) RadioHandle
- b) Communication side cover

3 User Interface

3.1 Keyboard

Keyboard MS60/TS60





008626.001















- a) Function keys F1-F6
- b) Function keys F7-F12
- c) ON/OFF
- d) Alphanumeric keys
- e) Backspace
- f) Esc
- g) Home
- h) Fn
- i) OK
- j) Arrow keys
- k) Enter
- l) Favourites
- m) Camera

Keys

| Key | Function |
|-----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Function keys F1-F6 | Correspond to six softkeys that appear on the bottom of the screen when the screen is activated. |
| Function keys F7-F12 | User definable keys to execute chosen commands or access chosen screens. |
| Alphanumeric keys | To type letters and numbers. |
| Camera | To capture an image with the camera. |
| Esc | Leaves the current screen without storing any changes. |
| Fn | Switches between the first and second level of function keys. |
| Enter | Selects the highlighted line and leads to the next logical menu / dialog. Starts the edit mode for editable fields. Opens a selectable list. |
| ON/OFF | If the instrument is already off: Turns on the instrument when held for 2 s. If the instrument is already on: Turns to Power Options menu when held for 2 s. |
| Favourites | Goes to a favourites menu. |
| Home | Switches to the Home Menu. Switches to the Windows CE Start Menu when pressing SHIFT at the same time. |

| Key | | Function |
|------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------|
| Arrow keys |  | Move the focus on the screen. |
| OK |  | Selects the highlighted line and leads to the next logical menu / dialog. Starts the edit mode for editable fields. Opens a selectable list. |

Key Combinations

| Key | | Function |
|-----------|---------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Fn | +  | Hold Fn while pressing  . Switch to Windows. |
| Fn | +  | Hold Fn while pressing  . Take a screenshot of the current screen. |
| Fn | + 1  | Hold Fn while pressing 1 . Increase the screen brightness. |
| Fn | + 4  | Hold Fn while pressing 4 . Decrease the screen brightness. |
| Fn | + 3  | Hold Fn while pressing 3 . Increase the volume for acoustic warning signals, beeps and keypresses on the field controller. |
| Fn | + 6  | Hold Fn while pressing 6 . Decrease the volume for acoustic warning signals, beeps and keypresses on the field controller. |
| Fn | + 7  | Hold Fn while pressing 7 . Lock/unlock the keyboard. |
| Fn | + 9  | Hold Fn while pressing 9 . Lock/unlock the touch screen. |
| Fn | + +  | Hold Fn while pressing  . Enter a plus sign instead of a minus sign. |
| Fn | +  | Hold Fn while pressing  . Turn the keyboard illumination on/off. |

3.2

Operating Principles

Keyboard and Touch Screen

The user interface is operated either by the keyboard or by the touch screen with supplied stylus. The workflow is the same for keyboard and touch screen entry, the only difference lies in the way information is selected and entered.

Operation by keyboard

Information is selected and entered using the keys. Refer to "3.1 Keyboard" for a detailed description of the keys on the keyboard and their function.

Operation by touch screen

Information is selected and entered on the screen using the supplied stylus.

| Operation | Description |
|----------------------------------------------------------------------|------------------------------------------------------|
| To select an item | Tap on the item. |
| To start the edit mode in editable fields | Tap on the editable field. |
| To highlight an item or parts of it for editing | Drag the supplied stylus from the left to the right. |
| To accept data entered into an editable field and exit the edit mode | Tap on the screen outside of the editable field. |
| To open a context-sensitive menu | Tap on the item and hold for 2 s. |

3.3

Autofocus Capability of Telescope Camera

Functionality

The autofocus button is located on the side cover.

| Action | Function |
|-------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Pressing 1x | A single autofocus is executed. The autofocus is related to the selected EDM mode (prism or non-prism measurements). |
| Pressing 2x | The refocus is executed. Based on the actual focus lense position, a refocus is performed. A refocus does a small movement of the focussing lense to find the best focus position. |
| Holding for 2 sec | The continuous autofocus is started. By pressing the button again or by turning the servofocus wheel, the continuous autofocus is stopped. |

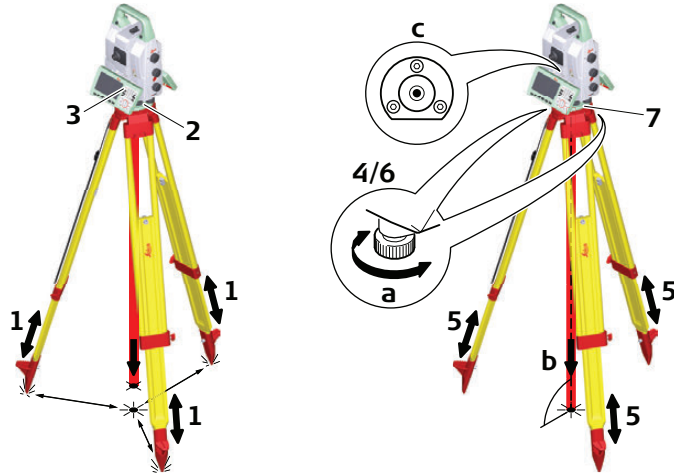
4

Operation

4.1

Setting Up the TS Instrument

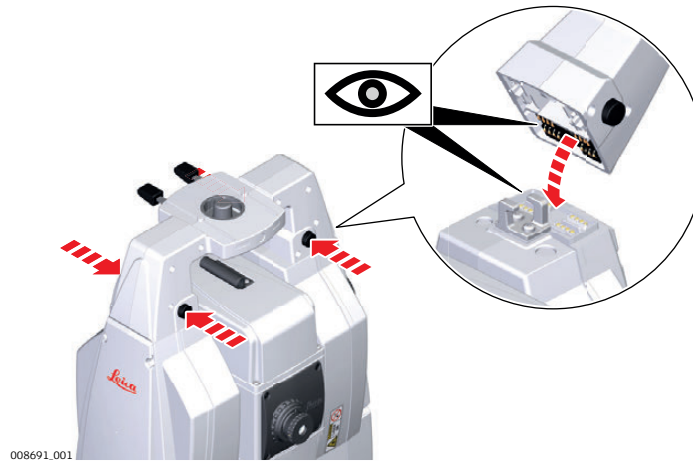
Instrument Setup Step-by-Step




008690.001

| Step | Description |
|------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Shield the instrument from direct sunlight and avoid uneven temperatures around the instrument. |
| 1. | Extend the tripod legs to allow for a comfortable working posture. Position the tripod above the marked ground point, centring it as good as possible. Ensure that the tripod plate is roughly horizontal. |
| 2. | Fasten the tribrach and instrument onto the tripod. |
| 3. | Turn on the instrument by pressing . Select Settings/TS instrument/Level & compensator to activate the laser plummet and electronic level. |
| 4. | Use the tribrach footscrews (a) to centre the plummet (b) above the ground point. |
| 5. | Adjust the tripod legs to level the circular level (c). |
| 6. | By using the electronic level, turn the tribrach footscrews (a) to level the instrument precisely. |
| 7. | Centre the instrument precisely over the ground point (b) by shifting the tribrach on the tripod plate. |
| 8. | Repeat steps 6. and 7. until the required accuracy is achieved. |

SmartStation Setup Step-by-Step



| Step | Description |
|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Place the GAD110 adapter for the GS15/GS14 antenna onto the instrument by simultaneously pressing and holding-in the four push buttons. |
|  | Ensure that the interface connection on the underside of the adapter is on the same side as the Communication side cover. |

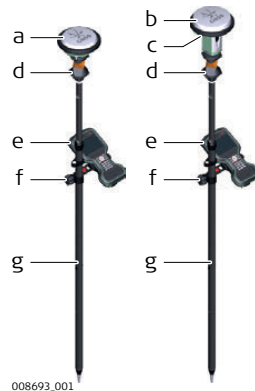


| Step | Description |
|------|-------------------------------------------------------------------------------------------------------------|
| 2. | Place the GS15/GS14 antenna onto the adapter by simultaneously pressing and holding-in the two press clips. |

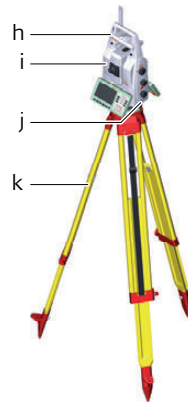
4.3

Setting Up SmartPole

SmartPole Setup using GS15/GS14



008693.001



- a) GS14 antenna
- b) GS15 antenna
- c) RTK slot-in device
- d) 360° prism
- e) Field controller on GHT66 holder (Alternative, not illustrated: tablet on GHT78 holder)
- f) GHT63 clamp
- g) GLS31 pole with snap-lock positions
- h) RH16/RH17 RadioHandle
- i) Instrument
- j) Communication side cover, integrated
- k) Tripod

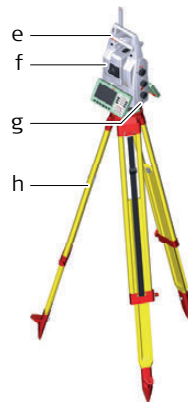
4.4

Setting up for Remote Control (with the RadioHandle)

Setup for Remote Control with RadioHandle



008694.001



- a) 360° prism
- b) Prism pole
- c) Field controller on GHT66 holder (Alternative, not illustrated: tablet on GHT78 holder)
- d) GHT63 clamp
- e) RadioHandle
- f) Instrument
- g) Communication side cover
- h) Tripod

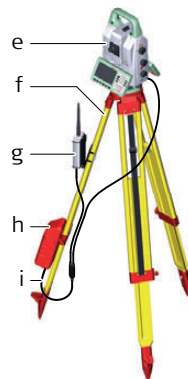
4.5

Setting up for Remote Control (with the TCPS29/30)

Setup for Remote Control with TCPS29/30




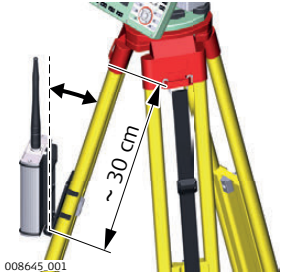


008695.001



- a) 360° prism
- b) Prism pole
- c) Field controller on GHT66 holder (Alternative, not illustrated: tablet on GHT78 holder)
- d) GHT63 clamp
- e) Instrument
- f) Tripod
- g) TCPS29/30
- h) External battery GEB371
- i) Y-cable

Mounting Base Radio to Tripod Step-by-Step

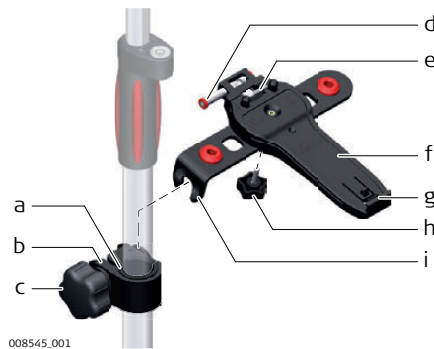
| Step | Description |
|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | The GHT43 tripod adapter is used to mount the TCPS29/30 to all Leica standard tripods, and to optimise the radio transmission performance. Attach the TCPS29/30 to the adapter and then attach the adapter to the tripod leg. |
| 2. | Adjust the angle of TCPS29/30 until it is vertical. |
| 3. | Adjust the location of the adapter on the tripod leg so that there are no metallic objects in the horizontal plane around the antenna.  Metallic objects near the antenna disturb radio transmissions. |
| 4. |  To achieve the best performance from the TCPS29/30, mount it in a vertical position on the tripod leg, approximately 30 cm from the top.  If the adapter is no longer able to retain its angle position, the adjustment bolt at the hinge can be tightened slightly.  |

4.6

Fixing the Field Controller to a Holder and Pole

Components of the GHT66 Holder

The GHT66 holder consists of the following components:




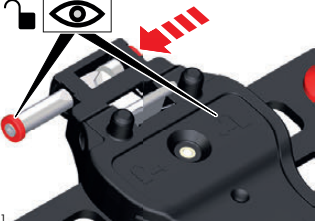
GHT63 clamp

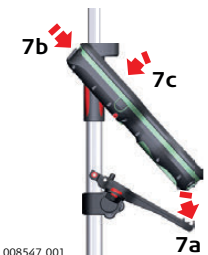
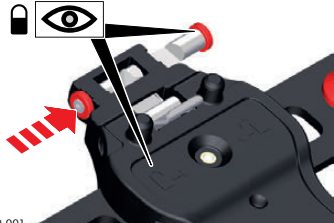
- a) Plastic sleeve
- b) Pole clamp
- c) Clamp bolt

GHT66 holder

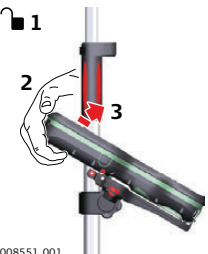
- d) Locking pin
- e) Top clip
- f) Mounting plate
- g) Bottom clip
- h) Tightening screw
- i) Mounting arm

Fixing the Field Controller and GHT66 to a Pole Step-by-step

| Step | Description |
|-------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | For an aluminium pole, fit the plastic sleeve to the pole clamp. |
| 1. | Insert the pole into the clamp hole. |
| 2. | Attach the holder to the clamp using the clamp bolt. |
| 3. | Adjust the angle and the height of the holder on the pole to a comfortable position. |
| 4. | Tighten the clamp with the clamp bolt. |
| 5. | Before placing the CS field controller onto the mounting plate, ensure that the locking pin is put into the unlocked position. To unlock the locking pin, push the locking pin to the left.  |
| 6. | Hold the CS field controller above the holder and lower the end of the CS field controller into the mounting plate. |

| Step | Description | |
|------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|
| 7. | Apply slight pressure in a downward direction and then lower the top part of the CS field controller until the unit is clicked into the holder. The guides of the mounting plate aid in this action. |  |
| 8. | After the CS field controller is placed onto the mounting plate, ensure that the locking pin is put into the locked position. To lock the locking pin, push the locking pin to the right. |  |

Detaching the Field Controller from a Pole Step-by-step

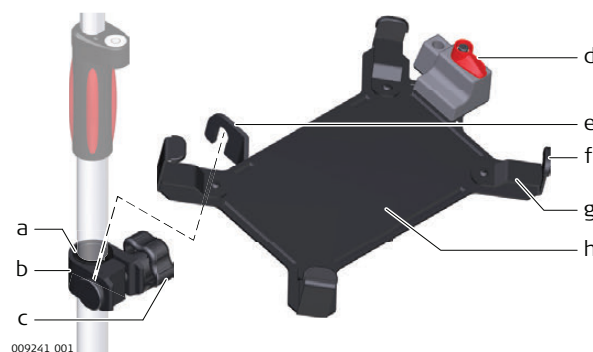
| Step | Description | |
|------|--------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|
| 1. | Unlock the locking pin by pushing the locking pin to the left of the mounting plate. | |
| 2. | Place your palm over the top of the field controller. | |
| 3. | While in this position, lift the top of the field controller from the holder. |  |

4.7

Fixing the CS35 Tablet to a Holder and Pole

Components of GHT63 Clamp and GHT78 Holder

For fixing the CS35 tablet to a pole you need the following components:





GHT63 clamp

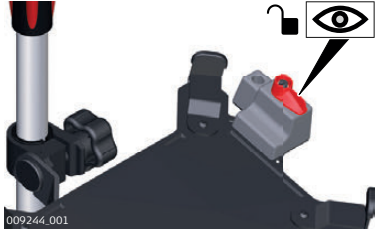
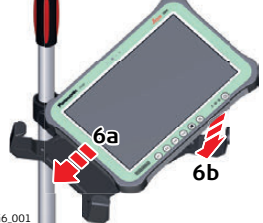

- a) Plastic sleeve
- b) Pole clamp
- c) Clamp bolt

GHT78 holder

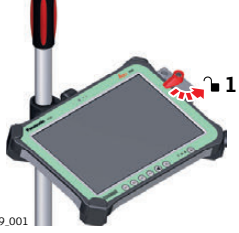

- d) Locking lever
- e) Mounting arm
- f) Mounting brackets
- g) Removable inserts
- h) Mounting plate

Fixing the CS35 Tablet and GHT78 to a Pole Step-by-Step

| Step | Description |
|-------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | For an aluminium pole, fit the plastic sleeve to the pole clamp. |
|  | If the 833343 hand strap with high corner guards is attached to the tablet, remove the inserts from the mounting brackets before fixing the tablet to the mounting plate. To untighten the screws of the removable inserts, use a 2.5 mm allen key. |

| Step | Description | |
|------|-------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|
| 1. | Insert the pole into the clamp hole. | |
| 2. | Attach the holder to the clamp using the clamp bolt. | |
| 3. | Adjust the angle and the height of the holder on the pole to a comfortable position. | |
| 4. | Tighten the clamp with the clamp bolt. | |
| 5. | Before placing the CS35 tablet onto the mounting plate, ensure that the locking lever is set to the unlocked position (see illustration). |  |
| 6. | Lower the left side of the tablet and slide it from right to left into the mounting brackets of the holder. |  |
| 7. | After placing the tablet onto the mounting plate, set the locking lever to the locked position (see illustration). |  |

Detaching the Tablet from the Holder/Pole Step-by-Step

| Step | Description | |
|------|--------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------|
| 1. | Set the locking lever of the GHT78 holder to the unlocked position. |  |
| 2. | Lift the right side of the tablet and slide the tablet to the right and out of the holder. |  |

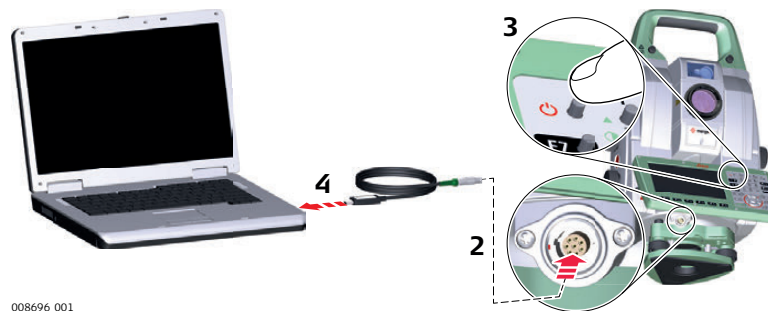


Microsoft ActiveSync (for PCs with Windows XP operating system) or Windows Mobile Device Center (for PCs with Windows Vista or Windows 7/Windows 8 operating system) is the synchronisation software for Windows mobile-based pocket PCs. Microsoft ActiveSync or Windows Mobile Device Center enables a PC and a Windows mobile-based pocket PC to communicate.

Install Leica USB Drivers

| Step | Description |
|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Start the PC. |
| 2. | Insert the Leica USB card. |
| 3. | Run the SetupViva&GR_USB_XX.exe to install the drivers necessary for Leica Nova devices. Depending on the version (32bit or 64bit) of the operating system on your PC, you have to select between the three setup files following: <ul style="list-style-type: none"> • SetupViva&GR_USB_32bit.exe • SetupViva&GR_USB_64bit.exe • SetupViva&GR_USB_64bit_itanium.exe The setup has to be run only once for all Leica Nova devices. |
| 4. | The Welcome to InstallShield Wizard for Leica Viva & GR USB drivers window appears. Ensure that all Leica Nova devices are disconnected from your PC before you continue! |
| 5. | Next> . |
| 6. | The Ready to Install the Program window appears. |
| 7. | Install. The drivers will be installed on your PC. For PCs with Windows Vista or Windows 7/Windows 8 operating system: If not already installed, Windows Mobile Device Center will be installed additionally. |
| 8. | The InstallShield Wizard Completed window appears. |
| 9. | Check I have read the instructions and click Finish to exit the wizard. |

Connect USB Cable to Computer for the First Time Step-by-Step

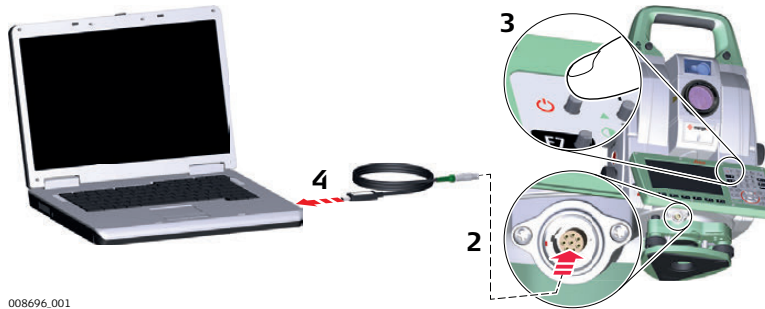


008696_001


| Step | Description |
|------|----------------------------------------------------------------------------------------------------------------------------------|
| 1. | Start the computer. |
| 2. | Plug the GEV234 or GEV261 cable into the lemo-port on the instrument. |
| 3. | Turn on the TS instrument. |
| 4. | Plug the GEV234 or GEV261 cable into the USB port of the computer. The Found New Hardware Wizard starts up automatically. |
| 5. | Check Yes, this time only. Next> . |

| Step | Description |
|------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 6. | Check Install the software automatically (Recommended). Next> . The software for Remote NDIS based LGS TS Device will be installed on your computer |
| 7. | Finish. |
| 8. | The Found New Hardware Wizard starts up automatically a second time. |
| 9. | Check Yes, this time only. Next> . |
| 10. | Check Install the software automatically (Recommended). Next> . The software for LGS TS USB Device will be installed on your computer. |
| 11. | Finish. |

Connect to Computer by USB Cable Step-by-Step





008696.001

| Step | Description |
|-------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------|
| 1. | Start the computer. |
| 2. | Plug the GEV234 or GEV261 cable into the instrument. |
| 3. | Turn on the instrument. |
| 4. | Plug the GEV234 or GEV261 cable into the USB port of the computer. |
|  | Active Sync or Windows Device Manager cannot be used with TS60 and MS60. |
| 5. | Press the Windows Start button. |
| 6. | Type <code>\\192.168.254.3\</code> into the search field. |
| 7. | Press Enter. <i>A file browser opens. You can now browse within the folders on the instrument.</i> |




4.9

Power Functions



Turning the Instrument On


Press and hold power key () for 2 s.
 The instrument must have a power supply.

Turning the Instrument Off

Press and hold power key () for 2 s.
 The instrument must be on.
 For instruments setup in permanent installations with external power sources, for example monitoring, ensure external power remains available until the instrument has successfully completed the power down process.

Power Options Menu

Press and hold power key () for 2 s to open **Power Options** menu.
 Instrument must be on.

| Option | Description |
|-----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Turn off | Turn TS instrument off. |
| Stand-by | Put TS instrument into stand-by mode.  In stand-by mode, the TS instrument shuts down and reduces power consumption. Rebooting from stand-by mode is quicker than a cold start after turning off. |
| Reset... | Performs one of the following options: <ul style="list-style-type: none">• Restart (restarts Windows EC7)• Reset Windows EC7 (resets Windows EC7 and communication settings to factory defaults)• Reset installed software (resets settings of all installed software)• Reset Windows EC7 and installed software (resets Windows EC7 and settings of all installed software) |

4.10

Batteries

4.10.1

Operating Principles

First-time Use / Charging Batteries

- The battery must be charged prior to using it for the first time.
- The permissible temperature range for charging is between 0°C to +40°C/ +32°F to +104°F. For optimal charging, we recommend charging the batteries at a low ambient temperature of +10°C to +20°C/+50°F to +68°F if possible.
- It is normal for the battery to become warm during charging. Using the chargers recommended by Leica Geosystems, it is not possible to charge the battery if the temperature is too high.
- For Li-Ion batteries, a single refreshing cycle is sufficient. We recommend carrying out a refreshing cycle when the battery capacity indicated on the charger or on a Leica Geosystems product deviates significantly from the actual battery capacity available.

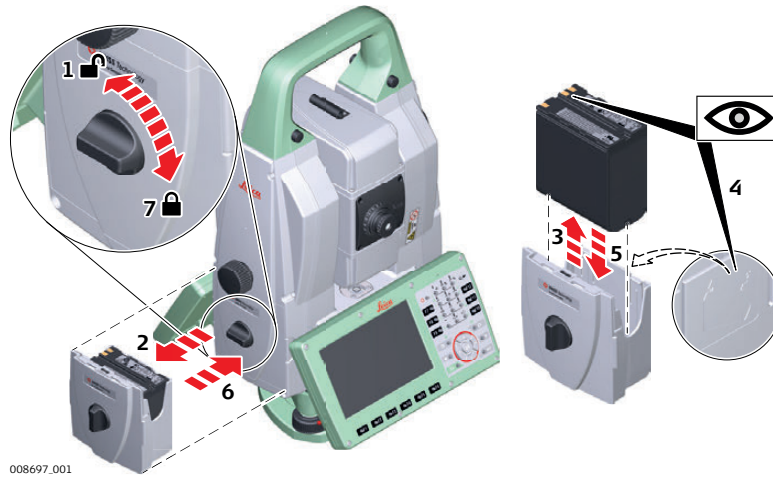
Operation / Discharging

- The batteries can be operated from -20°C to +55°C/-4°F to +131°F.
- Low operating temperatures reduce the capacity that can be drawn; high operating temperatures reduce the service life of the battery.

4.10.2

Battery for the TS Instrument

Change Battery Step-by-Step

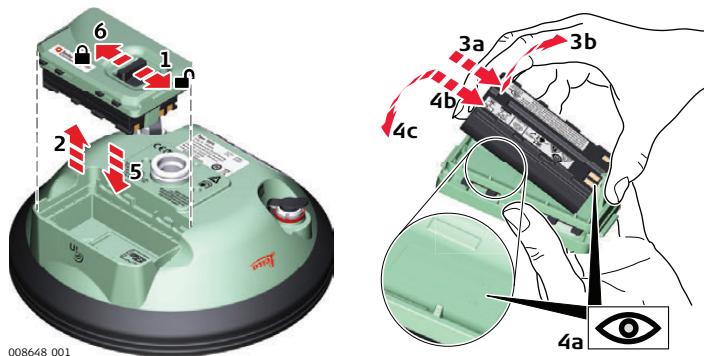


| Step | Description |
|------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Face the instrument so that the vertical drive screw is on the left. The battery compartment is below the vertical drive. Turn the knob to the vertical position, opening the lid of the battery compartment. |
| 2. | Pull out the battery housing. |
| 3. | Pull the battery from the battery housing. |
| 4. | A pictogram of the battery is displayed inside the battery housing. This pictogram is a visual aid to assist in placing the battery correctly. |
| 5. | Place the battery into the battery housing, ensuring that the contacts are facing outward. Click the battery into position. |
| 6. | Place the battery housing into the battery compartment. Push the battery housing in until it fits completely into the battery compartment. |
| 7. | Turn the knob to lock the battery compartment. Ensure that the knob is returned to its original horizontal position. |

4.10.3

Battery for SmartAntenna

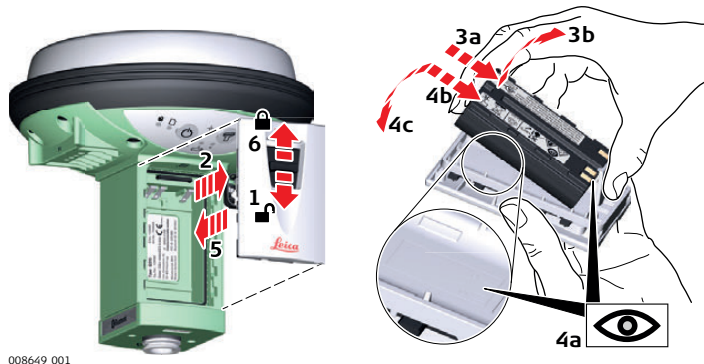
Change Battery Step-by-step (GS14)



| Step | Description |
|------|-------------------------------------------------------------------------------------------------------------|
| | The battery is inserted in the bottom part of the instrument. |
| 1. | Push the slide fastener of the battery compartment in the direction of the arrow with the open-lock symbol. |
| 2. | Remove the cover from the battery compartment. |

| Step | Description |
|------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 3. | To remove the battery, push the battery slightly upwards and at the same time pull out the bottom part of the battery. This releases the battery from its fixed position. |
| 4. | To insert the battery, slide the battery into the cover of the battery compartment with the battery contacts facing upwards. Push the battery downwards so that it locks into position. |
| 5. | Insert the cover of the battery compartment into the compartment. |
| 6. | Push the slide fastener in the direction of the arrow with the close-lock symbol. |

Change Battery Step-by-Step (GS15)



008649.001

| Step | Description |
|------|---------------------------------------------------------------------------------------------------------------------|
| | The batteries are inserted in the bottom part of the instrument. |
| 1. | Push the slide fastener of one of the battery compartments in the direction of the arrow with the open-lock symbol. |
| 2. | Remove the cover from the battery compartment. |
| 3. | With the battery contacts facing upwards, slide the battery into the cover of the battery compartment. |
| 4. | Push the battery upwards so that it locks into position. |
| 5. | Insert the cover of the battery compartment into the compartment. |
| 6. | Push the slide fastener in the direction of the arrow with the close-lock symbol. |

4.11

Working with the Memory Device



- Keep the card dry.
- Use it only within the specified temperature range.
- Do not bend the card.
- Protect the card from direct impacts.



Failure to follow these instructions could result in data loss and/or permanent damage to the card.

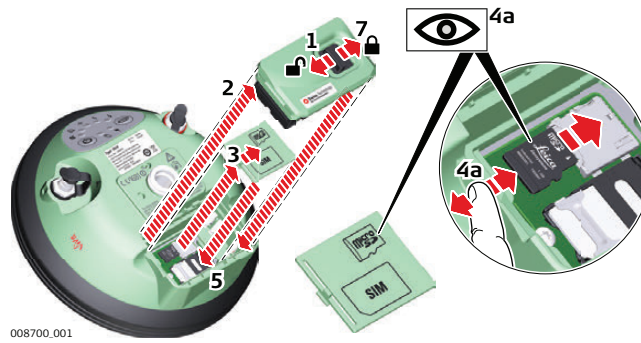
Insert and Remove an SD Card Step-by-Step

| Step | Description | |
|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------|
| | The SD card is inserted into a slot inside the Communication side cover of the instrument. | <p>008698_001</p> |
| 1. | Press the button on the side of the Communication side cover to unlock the communication compartment. | |
| | The lid opens automatically. | |
| 2. | To insert the SD card, slide it firmly into the SD slot until it clicks into position. The card must be held with the contacts at the top and facing toward the instrument. Do not force the card into the slot. | |
| 3. | To remove the SD card, gently press on the top of the card to release it from the slot. | |
| 4. | Close the lid by pushing the door down. Push the door on the marked part in the middle of the door. | |

Insert and Remove a USB Stick Step-by-Step

| Step | Description | |
|------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------|
| | The USB stick is inserted into the USB host port inside the Communication side cover of the instrument. | <p>008699_001</p> |
| 1. | Press the button on the side of the Communication side cover to unlock the communication compartment. | |
| | The lid opens automatically. | |
| 2. | To insert the USB stick, remove the cap of the USB stick. Hold the USB stick with the Leica logo facing you and slide it firmly into the USB host port until it clicks into position. Do not force the USB stick into the port. | |
| 3. | To remove the USB stick, slide the USB stick out of the port. | |
| 4. | Close the lid by pushing the door down. Push the door on the marked part in the middle of the door. | |

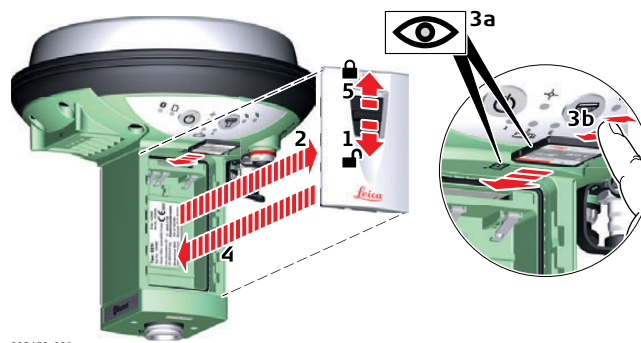
Insert a microSD card into GS14 step-by-step



008700.001


| Step | Description |
|------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Removing the microSD card while the GS14 is turned on can cause loss of data. Only remove the microSD card or unplug connecting cables when the GS14 is switched off. |
| | The microSD card is inserted into a slot inside the battery compartment of the instrument. |
| 1. | Push the slide fastener of the battery compartment in the direction of the arrow with the open-lock symbol. |
| 2. | Remove the cover from the battery compartment. |
| 3. | Press the latch of the SIM/microSD card cover and remove the cover. |
| 4. | Slide the microSD card with the logo facing upwards firmly into the slot until it clicks into position. |
| 5. | Insert the SIM/microSD card cover to cover slot. |
| 6. | Insert the cover over the battery compartment. |
| 7. | Push the slide fastener in the direction of the arrow with the close-lock symbol. |

Insert and Remove an SD Card into GS15 Step-by-Step



008652.001

| Step | Description |
|------|-------------------------------------------------------------------------------------------------------------|
| | The SD card is inserted into a slot inside the battery compartment 1 of the instrument. |
| 1. | Push the slide fastener of battery compartment 1 in the direction of the arrow with the open-lock symbol. |
| 2. | Remove the cover from battery compartment 1. |
| 3. | Slide the card firmly into the slot until it clicks into position. |
| | Do not force the card into the slot. The card should be held with the contacts upwards and facing the slot. |

| Step | Description |
|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | To remove the card, push the slide fastener of battery compartment 1 in the direction of the arrow with the open-lock symbol and remove the cover. Gently press on the top of the card to release it from the slot. Remove the SD card. |
| 4. | Insert the cover into battery compartment 1. |
| 5. | Push the slide fastener in the direction of the arrow with the close-lock symbol. |

4.12

Working with the RTK Device (SmartStation)

Devices Fitting into the GS15 GNSS Instrument

Digital cellular phones fitting into the GS15 GNSS instrument

| Digital cellular phone | Device |
|------------------------|--------|
| Telit UC864-G | SLG1 |




Radios fitting into the GS15 GNSS instrument

| Radio | Device |
|-------------------------------|--------|
| Satellite M3-TR1, transceiver | SLR5 |

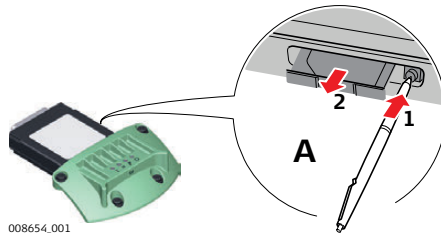
Insert and Remove a Slot-in-Device Step-by-Step



008653.001

| Step | Description |
|-------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | Turn over the GS15 to gain access to the slot-in-device compartment. |
| 1. | Loosen the screws of the compartment cover with the supplied Allen key. |
| 2. | Remove the compartment cover. |
| 3. | Attach the slot-in-device to the compartment cover. |
| 4. | Insert the compartment cover into the compartment (port P3). |
| 5. | Tighten the screws.  All screws have to be tightened to ensure that the instrument is waterproof. |
|  | For the equipment setup as real-time base station with radio, it's recommended to use an external radio antenna mounted on a second tripod. This increases the height of the radio antenna and therefore maximises radio coverage. |

Insert and Remove a SIM Card Step-by-Step



008654.001

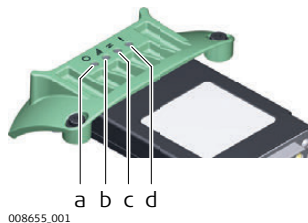
| Step | Description |
|------|----------------------------------------------------------------------------------------------------|
| | The SIM card is inserted into a slot on the side of the SLG1. |
| | Take the SIM card and a pen. |
| 1. | Using the pen, press the small button of the SIM card slot to eject the SIM card holder. |
| 2. | Take the SIM card holder out off the SLG1. |
| 3. | Place the SIM card into the SIM card holder, the chip facing up. |
| 4. | Insert the SIM card holder into the SIM card slot, the chip facing the connectors inside the slot. |

LED Indicators

Description

Each slot-in-device for a radio or digital cellular phones has **L**ight **E**mitting **D**iode indicators on the bottom side. They indicate the basic device status.

Diagram



008655.001

- a) Power LED
- b) Signal strength LED
- c) Data transfer LED
- d) Mode LED, available for Satel radios

Description of the LEDs

| IF the | on | is | THEN |
|---------------------|---------------------------|-------------------------------|-----------------------------------------------------------------------------------------------------------|
| Mode LED | SLR5 with Sateline M3-TR1 | red | the device is in the programming mode controlled from the PC via cable. |
| Data transfer LED | any device | off | data is not being transferred. |
| | | flashing green | data is being transferred. |
| Signal strength LED | SLG1 with Telit UC864-G | red | call is in progress. |
| | | red: long flash, long break | no SIM card inserted, no PIN entered or network search, user authentication or network login in progress. |
| | | red: short flash, long break | logged on to network, no call in progress. |
| | | red: flashing red, long break | GPRS PDP context activated. |
| | | red: long flash, short break | Packet switched data transfer is in progress. |
| | | off | device is off. |

| IF the | on | is | THEN |
|-----------|-----------------------------------|--------------|---------------------------------------------------------------------------------------------------------------|
| | SLR5 with Satellite M3- TR1 | red | the communication link, Data Carrier Detection , is okay on the roving instrument. |
| | | flashing red | the communication link, Data Carrier Detection , is okay on the roving instrument, but signal is weak. |
| | | off | the DCD is not okay. |
| Power LED | any device | off | power is off. |
| | | green | power is okay. |

4.13

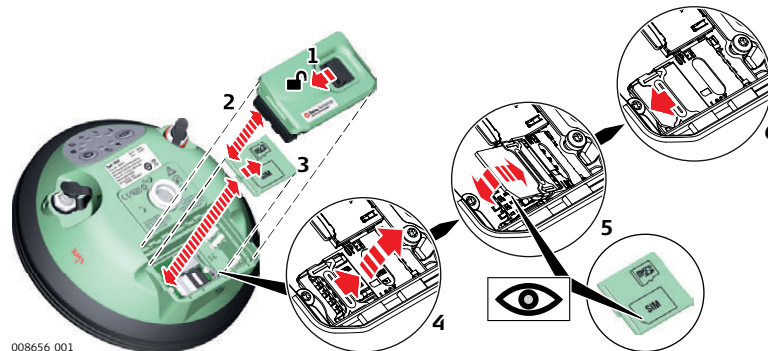
Working with the RTK Device

Devices Fitted into the GS14 GNSS Instrument

Depending on the GS14 model one or two of the following devices are integrated:

| Type | Device |
|-----------------|-------------------------------|
| 2G GSM | Cinterion BGS2-W |
| 3.75G GSM/UMTS | Cinterion PHS8-P/PHS8-J |
| 3.75G GSM/UMTS | Cinterion PXS8 |
| RX UHF radio | Satel OEM20, receive |
| RX/TX UHF radio | Satel OEM22, receive/transmit |

Insert and Remove a SIM Card Step-by-Step



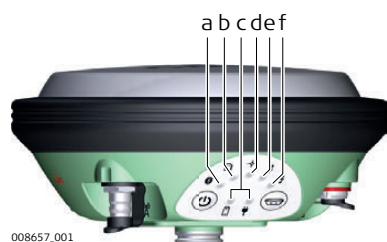
| Step | Description |
|------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Inserting/removing the SIM card while the GS14 is turned on can result in permanent damage to the card. Only insert/remove the SIM card when the GS14 is switched off. |
| | The SIM card is inserted into a slot inside the battery compartment. |
| 1. | Push the slide fastener of the battery compartment in the direction of the arrow with the open-lock symbol. |
| 2. | Remove the cover from battery compartment. |
| 3. | Press the latch of the SIM/microSD card cover and remove the cover. |
| 4. | Push the SIM card holder in the direction of the OPEN arrow and flip it up. |
| 5. | Place the SIM card into the SIM card holder, the chip facing the connectors inside the slot - as shown on the SIM/microSD card cover. Press the SIM card holder down. |
| 6. | Push the SIM card holder in the direction of the LOCK arrow to close. |

LED Indicators

Description

The GS14 GNSS instrument has Light Emitting Diode indicators. They indicate the basic instrument status.

Diagram



008657.001

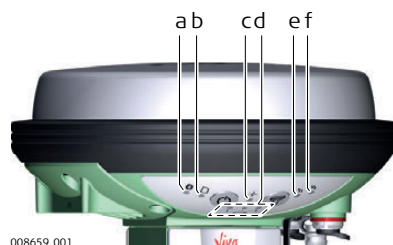
- a) Bluetooth LED
- b) Storage LED
- c) Power LEDs
- d) Position LED
- e) RTK Base LED
- f) RTK Rover LED

LED Indicators on GS15

Description

The GS15 has Light Emitting Diode indicators. They indicate the basic instrument status.

Diagram



008659.001

- a) Bluetooth LED
- b) Storage LED
- c) Position LED
- d) Power LEDs
- e) RTK Base LED
- f) RTK Rover LED

Description of the LEDs

| IF the | is | THEN |
|---------------|-------------------|-------------------------------------------------------------------------|
| Bluetooth LED | green | Bluetooth is in data mode and ready for connecting. |
| | purple | Bluetooth is connecting. |
| | blue | Bluetooth has connected. |
| Storage LED | off | no SD card is inserted or GS15 is switched off. |
| | green | SD card is inserted but no raw data is being logged. |
| | flashing green | raw data is being logged. |
| | flashing yellow | raw data is being logged but only 10% memory left. |
| | flashing red | raw data is being logged but only 5% memory left. |
| | red | SD card is full, no raw data is being logged. |
| | fast flashing red | no SD card is inserted but GS15 is configured to log raw data. |
| Position LED | off | no satellites are tracked or GS15 is switched off. |
| | flashing yellow | less than four satellites are tracked, a position is not yet available. |
| | yellow | a navigated position is available. |

| IF the | is | THEN |
|--------------------------------------------|-------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------|
| | flashing green | a code-only position is available. |
| | green | a fixed RTK position is available. |
| Power LED (active battery ^{*1}) | off | battery is not connected, flat or GS15 is switched off. |
| | green | power is 40% - 100%. |
| | yellow | power is 20% - 40%. The remaining time for which enough power is available depends on the type of survey, the temperature and the age of the battery. |
| | red | power is 5% - 20%. |
| | fast flashing red | power is low (< 5%). |
| Power LED (passive battery ^{*2}) | off | battery is not connected, flat or the GS15 is switched off. |
| | flashing green | power is 40% - 100%. LED is green for 1 s every 10 s. |
| | flashing yellow | power is 20% - 40%. LED is yellow for 1 s every 10 s. |
| | flashing red | power is less than 20%. LED is red for 1 s every 10 s. |
| RTK Rover LED | off | GS15 is in RTK base mode or GS15 is switched off. |
| | green | GS15 is in rover mode. No RTK data is being received at the interface of the communication device. |
| | flashing green | GS15 is in rover mode. RTK data is being received at the interface of the communication device. |
| RTK Base LED | off | GS15 is in RTK rover mode or GS15 is switched off. |
| | green | GS15 is in RTK base mode. No RTK data is being passed to the RX/TX interface of the communication device. |
| | flashing green | GS15 is in RTK base mode. Data is being passed to the RX/TX interface of the communication device. |

*1 The battery, which currently powers the GS15 GNSS instrument.

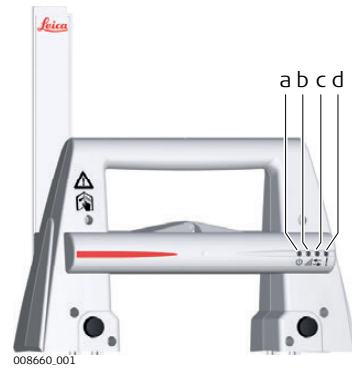
*2 Other batteries, which are inserted or connected but are not currently power the GS15 GNSS instrument.

LED Indicators on RadioHandle

Description

The RadioHandle has Light Emitting Diode indicators. They indicate the basic Radio-Handle status.

Diagram of the LED Indicators



- a) Power LED
- b) Link LED
- c) Data Transfer LED
- d) Mode LED

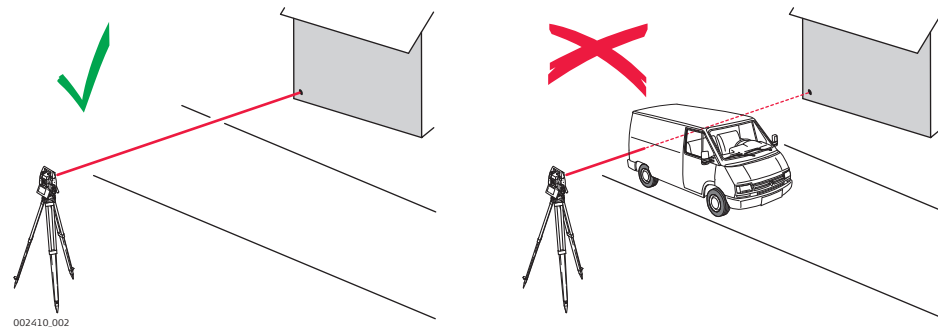
Description of the LED Indicators

| IF the | is | THEN |
|-------------------|-------------------------|--------------------------------------------|
| Power LED | off | power is off. |
| | green | power is on. |
| Link LED | off | no radio link to field controller. |
| | red | radio link to field controller. |
| Data Transfer LED | off | no data transfer to/from field controller. |
| | green or green flashing | data transfer to/from field controller. |
| Mode LED | off | data mode. |
| | red | configuration mode. |

4.15

Guidelines for Correct Results

Distance Measurement



When measurements are being made using the red laser EDM, the results can be influenced by objects passing between the EDM and the intended target surface. This occurs because reflectorless measurements are made to the first surface returning sufficient energy to allow the measurement to take place. For example, if the intended target surface is the surface of a building, but a vehicle passes between the EDM and the target surface as the measurement is triggered, the measurement may be made to the side of the vehicle. The result is the distance to the vehicle, not to the surface of the building.

If using the long range measurement mode (> 1000 m, > 3300 ft, available on TS60) to prisms, and an object passes within 30 m of the EDM as the measurement is triggered, the distance measurement may be similarly effected due to the strength of the laser signal.



Very short distances can also be measured reflectorless in **Prism** mode to well reflecting natural targets. The distances are corrected with the additive constant defined for the active reflector.



CAUTION

Due to laser safety regulations and measuring accuracy, using the Long Range Reflectorless EDM is only allowed to prisms that are more than 1000 m (3300 ft) away.



Accurate measurements to prisms should be made in **Prism** mode.



When a distance measurement is triggered, the EDM measures to the object which is in the beam path at that moment. If a temporary obstruction, for example a passing vehicle, heavy rain, fog or snow is between the instrument and the point to be measured, the EDM may measure to the obstruction.



Do not measure with two instruments to the same target simultaneously to avoid getting mixed return signals.

ATRplus/Lock

Instruments equipped with an ATRplus sensor permit automatic angle and distance measurements to prisms. The prism is sighted with the optical sight. After initiating a distance measurement, the instrument sights the prism centre automatically. Vertical and horizontal angles and the distance are measured to the centre of the prism. The lock mode enables the instrument to follow a moving prism.



As with all other instrument errors, the collimation error of the automatic aiming must be redetermined periodically. Refer to "5 Check & Adjust" about checking and adjusting instruments.



When a measurement is triggered while the prism is still moving, distance and angle measurements may not be made for the same position and coordinates may vary.



If the prism location is changed too quickly, the target may be lost. Make sure that the speed does not exceed the figure given in the technical data.

Motorised Positioning

Unstable instrument setup conditions or small vibrations of the instrument resulting from heavy traffic or construction activities in the vicinity of the instrument may lead to an abandonment of the instrument's positioning before the final position is reached. Ensure that the instrument setup is stable, especially if steep sightings are necessary. If an incomplete positioning is indicated check the position deviation and repeat the according positioning command.

5

Check & Adjust

5.1

Overview

Description

Leica Geosystems instruments are manufactured, assembled and adjusted to the best possible quality. Quick temperature changes, shock or stress can cause deviations and decrease the instrument accuracy. It is therefore recommended to check and adjust the instrument from time to time. This check and adjust can be done in the field by running through specific measurement procedures. The procedures are guided and must be followed carefully and precisely as described in the following chapters. Some other instrument errors and mechanical parts can be adjusted mechanically.

Electronic Adjustment

The following instrument errors can be checked and adjusted electronically:

| | |
|------------------|-----------------------------------------------------------------------------------------------------------------------------------------|
| l, t | Compensator longitudinal and transversal index errors |
| i | Vertical index error, related to the standing axis |
| c | Horizontal collimation error, also called line of sight error |
| a | Tilting axis error |
| ATRplus | ATRplus zero point error for Hz and V |
| Telescope camera | Telescope camera zero point error, relation between principal point of telescope camera and crosshair in telescope in Hz and V - option |

If the compensator and the horizontal corrections are activated in the instrument configuration, every angle measured in the daily work is corrected automatically. Check whether the tilt correction and the horizontal correction are turned on. The results are displayed as errors but used with the opposite sign as corrections when applied to measurements.

Mechanical Adjustment

The following instrument parts can be adjusted mechanically:

- Circular level on instrument and tribrach
- Optical plummet - option on tribrach
- Allen screws on tripod

Precise Measurements

To get precise measurements in the daily work, it is important:

- To check and adjust the instrument from time to time.
- To take high precision measurements during the check and adjust procedures.
- To measure targets in two faces. Some of the instrument errors are eliminated by averaging the angles from both faces.



During the manufacturing process, the instrument errors are carefully determined and set to zero. As mentioned above, these errors can change and it is highly recommended to redetermine them in the following situations:

- Before the first use
 - Before every high precision survey
 - After rough or long transportation
 - After long working periods
 - After long storage periods
 - If the temperature difference between current environment and the temperature at the last calibration is more than 20°C
-

Summary of Errors to be Adjusted Electronically

| Instrument error | Effects Hz | Effects V | Elimination with two face measurement | Automatically corrected with proper adjustment |
|-----------------------------------|------------|-----------|---------------------------------------|------------------------------------------------|
| c - Line of sight error | ✓ | - | ✓ | ✓ |
| a - Tilting axis error | ✓ | - | ✓ | ✓ |
| l - Compensator index error | - | ✓ | ✓ | ✓ |
| t - Compensator index error | ✓ | - | ✓ | ✓ |
| i - Vertical index error | - | ✓ | ✓ | ✓ |
| ATRplus Collimation error | ✓ | ✓ | - | ✓ |
| Co-axial camera collimation error | ✓ | ✓ | ✓ | ✓ |

5.2

Preparation



Before determining the instrument errors, the instrument has to be levelled using the electronic level.

The tribrach, the tripod and the underground should be stable and secure from vibrations or other disturbances.



The instrument should be protected from direct sunlight to avoid thermal warming.

It is also recommended to avoid strong heat shimmer and air turbulence. The best conditions are early in the morning or with overcast sky.



Before starting to work, the instrument has to become acclimatised to the ambient temperature. Approximately two minutes per °C of temperature difference from storage to working environment, but at least 15 min, should be taken into account.



Even after adjustment of the ATRplus, the crosshairs may not be positioned exactly on the centre of the prism after an ATRplus measurement has been completed. This outcome is a normal effect. To speed up the ATRplus measurement, the telescope is normally not positioned exactly on the centre of the prism. These small deviations/ATRplus offsets, are calculated individually for each measurement and corrected electronically. This means that the horizontal and vertical angles are corrected twice: first by the determined ATRplus errors for Hz and V, and then by the individual small deviations of the current aiming.

Next Step

| IF the task is to | THEN |
|-------------------------------------------|--------------------------------------------------------------------------------|
| adjust a combination of instrument errors | Refer to "5.3 Combined Adjustment (l, t, i, c, ATRplus and Telescope Camera)". |
| adjust the tilting axis | Refer to "5.4 Tilting Axis Adjustment (a)". |
| adjust the circular level | Refer to "5.5 Adjusting the Circular Level of the Instrument and Tribrach". |
| adjust the laser/optical plummet | Refer to "5.7 Inspecting the Laser Plummet of the Instrument". |
| adjust the tripod | Refer to "5.8 Servicing the Tripod". |



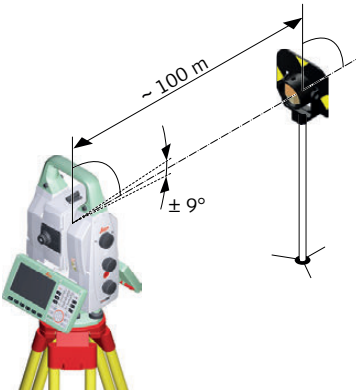
Description

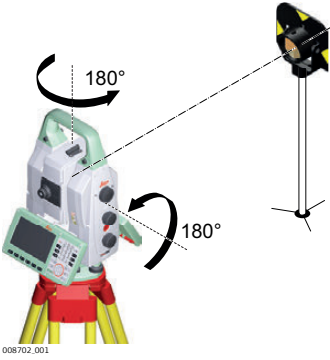



The combined adjustment procedure determines the following instrument errors in one process:

| | |
|---------------------|-----------------------------------------------------------------|
| I, t | Compensator longitudinal and transversal index errors |
| i | Vertical index error, related to the standing axis |
| c | Horizontal collimation error, also called line of sight error |
| ATRplus Hz | ATRplus zero point error for horizontal angle |
| ATRplus V | ATRplus zero point error for vertical angle |
| Telescope camera Hz | Telescope camera zero point error for horizontal angle - option |
| Telescope camera V | Telescope camera zero point error for vertical angle - option |

Combined Adjustment Procedure Step-by-Step

The following table explains the most common settings.

| Step | Description |
|------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Leica Captivate - Home: Settings\TS instrument\Check & adjust |
| 2. | Check & Adjust Select the option: Check & adjust the compensator, index error, line of sight error, automatic target aiming & telescope camera |
| 3. | Next |
| 4. | Face I measurement If Calibrate the automatic target aiming is checked and an ATRplus is available, the adjustment will include the determination of the ATRplus Hz and V adjustment errors.  Use a clean Leica standard prism as the target. Do not use a 360° prism. If Calibrate the telescope camera is checked and a telescope camera is available, the adjustment includes the determination of the telescope camera zero point.  Use a clean Leica standard prism as the target. Do not use a 360° prism. |
| 5. |  Aim the telescope accurately at a target at about 100 m distance. The target must be positioned within $\pm 9^\circ/\pm 10$ gon of the horizontal plane. The procedure can be started in any face. |

| Step | Description |
|------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 6. | <p>Measure to measure and to continue to the next screen.</p>  <p>If Calibrate the telescope camera has been checked, aim at the same target accurately with the telescope camera using the view finder and the digital crosshair on the display. Measure to measure and to continue to the next screen.</p> <p> The fine pointing has to be performed manually in both faces.</p> |
| 7. | <p>Face II measurement</p> <p>Measure to measure the same target in the other face.</p> <p>If Calibrate the telescope camera has been checked, aim at the same target accurately with the telescope camera using the view finder and the digital crosshair on the display. Measure measure to the target and to calculate the instrument errors.</p> <p> If one or more errors are bigger than the predefined limits, the procedure must be repeated. All measurements of the current run are rejected and none of them is averaged with the results from previous runs.</p> |
| 8. | <p>Adjustment Status</p> <p>Number of measurements: Shows the number of runs completed. One run consists of a measurement in face I and face II.</p> <p>I Component quality (1 σ): and similar lines show the standard deviations of the determined adjustment errors. The standard deviations can be calculated from the second run onwards.</p> <p> Measure at least two runs.</p> |
| 9. | <p>Next to continue with the check & adjust procedure.</p> |
| 10. | <p>Select Add another calibration loop if more runs have to be added. Next and continue with step 4.</p> <p>OR</p> <p>Select Finish the calibration & store the results to finish the calibration process. Next to view the adjustment results.</p> |
| 11. | <p>Select Finish to accept the results. No more runs can be added later.</p> <p>OR</p> <p>Select Redo to decline all measurements and to repeat all calibration runs.</p> <p>OR</p> <p>Back returns to the previous screen.</p> |

Next Step

| IF the results are | THEN |
|------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| to be stored | If the Use status is set to Yes, Next overwrites the old adjustment errors with the new ones. |
| to be determined again | Redo rejects all new determined adjustment errors and repeats the whole procedure. Refer to paragraph "Combined Adjustment Procedure Step-by-Step". |

5.4

Tilting Axis Adjustment (a)


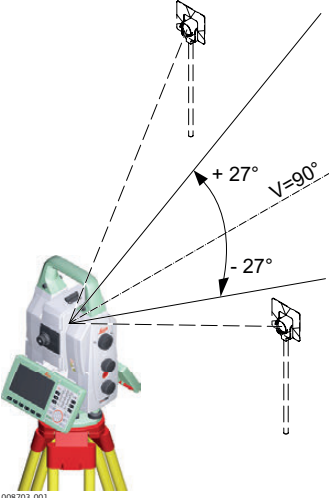
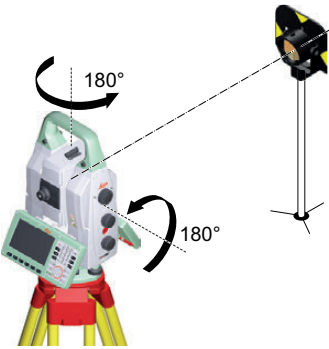


Description


This adjustment procedure determines the following instrument error:

a Tilting axis error

Determination of Tilting Axis Error Step-by-Step

The following table explains the most common settings.

| Step | Description |
|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | Determine the horizontal collimation error (c) before starting this procedure. |
| 1. | Leica Captivate - Home: Settings\TS instrument\Check & adjust |
| 2. | Check & Adjust Select the option: Check & adjust the tilting axis |
| 3. | <p>Face I measurement</p>  <p>Aim the telescope accurately at a target at about 100 m distance (or at least 20 m). The target must be positioned at least 27°/30 gon above or beneath the horizontal plane. The procedure can be started in any telescope face.</p> |
| 4. |  <p>Measure to measure and to continue to the next screen.  The fine pointing must be performed manually in both faces.</p> |
| 5. | <p>Face II measurement</p> <p>Measure to measure the same target in the other face and to calculate the tilting axis error.</p> |
|  | If the error is bigger than the predefined limit, the procedure must be repeated. The tilting axis measurements of the current run are then rejected and not averaged with the results from previous runs. |
| 6. | <p>Adjustment Status</p> <p>Number of measurements: Shows the number of runs completed. One run consists of a measurement in face I and face II.</p> <p>a T-axis quality (1 σ): shows the standard deviation of the determined tilting axis error. The standard deviation can be calculated from the second run onwards.</p> |

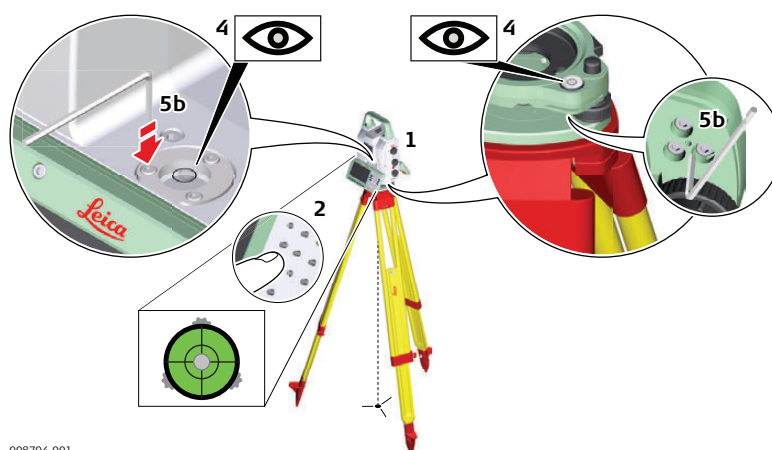
| Step | Description |
|-----------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  | Measure at least two runs. |
| 7. | Next to continue with the check & adjust procedure. |
| 8. | Select Add another calibration loop if more runs have to be added. Next and continue with step 3. OR Select Finish the calibration & store the results to finish the calibration process. No more runs can be added later. Next to view the adjustment results. |
| 9. | Select Finish to accept the results. No more runs can be added later. OR Select Redo to decline all measurements and to repeat all calibration runs. |

Next Step

| IF the results are | THEN |
|------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|
| to be stored | Next overwrites the old tilting axis error with the new one. |
| to be determined again | Redo rejects the new determined tilting axis error and repeats the whole procedure. Refer to paragraph "Tilting Axis Adjustment (a)". |


5.5 Adjusting the Circular Level of the Instrument and Tribrach

Adjusting the Circular Level Step-by-Step



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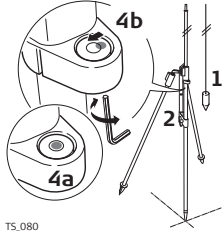

| Step | Description |
|------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Place and secure the instrument into the tribrach and onto a tripod. |
| 2. | Using the tribrach footscrews, level the instrument with the electronic level. |
| 3. | Select Settings\TS instrument\Level & compensator to access the Level & Compensator screen. |
| 4. | Check the position of the circular level on the instrument and tribrach. |
| 5. | a) If both circular levels are centred, no adjustments are necessary b) If one or both circular levels are not centred, adjust as follows: |
| | Instrument: If it extends beyond the circle, use the supplied allen key to centre it with the adjustment screws. Turn the instrument by 200 gon (180°). Repeat the adjustment procedure if the circular level does not stay centred. |

| Step | Description |
|-----------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------|
| | Tribrach: If it extends beyond the circle, use the supplied allen key to centre it with the adjustment screws. |
|  | After the adjustments, all adjusting screws must have the same tightening tension and no adjusting screw should be loose. |

5.6

Adjusting the Circular Level of the Prism Pole

Adjusting the Circular Level Step-by-Step

| Step | Description | |
|-----------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|
| 1. | Suspend a plumb line. |  |
| 2. | Use a pole bipod, to align the prism pole parallel to the plumb line. | |
| 3. | Check the position of the circular level on the prism pole. | |
| 4. | a) If the circular level is centred, no adjustment is necessary. b) If the circular level is not centred, use an allen key to centre it with the adjustment screws. | |
|  | After the adjustments, all adjusting screws must have the same tightening tension and no adjusting screw should be loose. | |

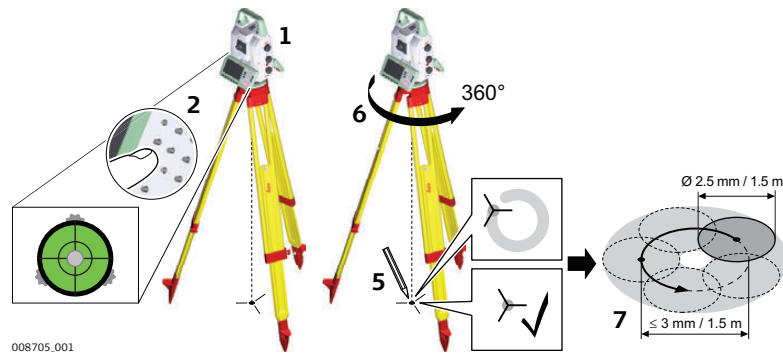
5.7

Inspecting the Laser Plummet of the Instrument




The laser plummet is located in the vertical axis of the instrument. Under normal conditions of use, the laser plummet does not need adjusting. If an adjustment is necessary due to external influences, return the instrument to any Leica Geosystems authorised service workshop.

Inspecting the Laser Plummet Step-by-Step



The following table explains the most common settings.

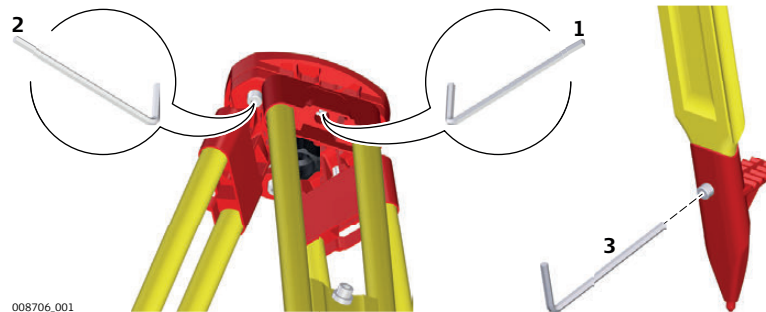
| Step | Description |
|------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. | Place and secure the instrument into the tribrach and onto a tripod. |
| 2. | Using the tribrach footscrews, level the instrument with the electronic level. |
| 3. | Select Settings \TS instrument\ Level & compensator to access the Level & Compensator screen. |
| 4. | The laser plummet is switched on when the Level & Compensator screen is entered. Adjust the laser plummet intensity. Inspection of the laser plummet should be carried out on a bright, smooth and horizontal surface, like a sheet of paper. |

| Step | Description |
|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 5. | Mark the centre of the red dot on the ground. |
| 6. | Turn the instrument through 360° slowly, carefully observing the movement of the red laser dot. |
|  | The maximum diameter of the circular movement described by the centre of the laser point must not exceed 3 mm at a distance of 1.5 m. |
| 7. | If the centre of the laser dot describes a perceptible circular movement, or moves more than 3 mm away from the point which was first marked, an adjustment may be required. Inform your nearest Leica Geosystems authorised service workshop. Depending on brightness and surface, the diameter of the laser dot can vary. At 1.5 m, it is about 2.5 mm. |

5.8


Servicing the Tripod

Servicing the Tripod Step-by-Step



008706.001

The following table explains the most common settings.

| Step | Description |
|-------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------|
|  | The connections between metal and timber components must always be firm and tight. |
| 1. | Tighten the leg cap screws moderately, with the supplied allen key. |
| 2. | Tighten the articulated joints on the tripod head enough to keep the tripod legs open when lifting the tripod off the ground. |
| 3. | Tighten the allen screws of the tripod legs. |

6 Care and Transport

6.1 Transport

| | |
|-----------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Transport in the field | When transporting the equipment in the field, always make sure that you <ul style="list-style-type: none">• either carry the product in its original transport container,• or carry the tripod with its legs splayed across your shoulder, keeping the attached product upright. |
| Transport in a road vehicle | Never carry the product loose in a road vehicle, as it can be affected by shock and vibration. Always carry the product in its transport container, original packaging or equivalent and secure it. |
| Shipping | When transporting the product by rail, air or sea, always use the complete original Leica Geosystems packaging, transport container and cardboard box, or its equivalent, to protect against shock and vibration. |
| Shipping, transport of batteries | When transporting or shipping batteries, the person responsible for the product must ensure that the applicable national and international rules and regulations are observed. Before transportation or shipping, contact your local passenger or freight transport company. |
| Field adjustment | Periodically carry out test measurements and perform the field adjustments indicated in the User Manual, particularly after the product has been dropped, stored for long periods or transported. |

6.2 Storage

| | |
|-------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Product | Respect the temperature limits when storing the equipment, particularly in summer if the equipment is inside a vehicle. Refer to "7 Technical Data" for information about temperature limits. |
| Field adjustment | After long periods of storage inspect the field adjustment parameters given in this user manual before using the product. |
| Li-Ion batteries | <ul style="list-style-type: none">• Refer to "Technical Data" for information about storage temperature range.• Remove batteries from the product and the charger before storing.• After storage recharge batteries before using.• Protect batteries from damp and wetness. Wet or damp batteries must be dried before storing or use.• A storage temperature range of 0°C to +30°C / +32°F to +86°F in a dry environment is recommended to minimize self-discharging of the battery.• At the recommended storage temperature range, batteries containing a 30% to 50% charge can be stored for up to one year. After this storage period the batteries must be recharged. |

6.3 Cleaning and Drying

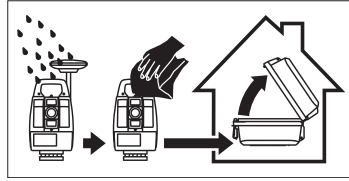
| | |
|--------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Product and accessories | <ul style="list-style-type: none">• Blow dust off lenses and prisms.• Never touch the glass with your fingers.• Use only a clean, soft, lint-free cloth for cleaning. If necessary, moisten the cloth with water or pure alcohol. Do not use other liquids; these can attack the polymer components. |
|--------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

Fogging of prisms

Prisms that are cooler than the ambient temperature tend to fog. It is not enough simply to wipe them. Keep them for some time inside your jacket or in the vehicle to allow them to adjust to the ambient temperature.

Damp products

Dry the product, the transport container, the foam inserts and the accessories at a temperature not greater than 40°C /104°F and clean them. Remove the battery cover and dry the battery compartment. Do not repack until everything is completely dry. Always close the transport container when using in the field.



Cables and plugs

Keep plugs clean and dry. Blow away any dirt lodged in the plugs of the connecting cables.

6.4

Maintenance



An inspection of the product must be done in a Leica Geosystems authorised service workshop. Leica Geosystems recommends an inspection of the product every 12 months.

As MS60/TS60 instruments are equipped with a self-surveillance system designed for maximum motor performance and long maintenance cycles Leica Geosystems recommends inspection of the product whenever indicated in the message line of the user interface.

7 Technical Data

7.1 Angle Measurement

Accuracy

| Type | std. dev. Hz, V, ISO 17123-3 | | Display least count | |
|------------|------------------------------|--------|---------------------|--------|
| | ["] | [mgon] | ["] | [mgon] |
| TS60 R1000 | 0.5 | 0.15 | 0.1 | 0.01 |
| MS60 R2000 | 1 | 0.30 | 0.1 | 0.01 |


Characteristics

Absolute, continuous, diametric.

7.2 Distance Measurement with Reflectors


Range

For TS60 - R1000:

| Reflector | Range A | | Range B | | Range C | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|------|---------|-------|---------|-------|
| | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| Standard prism (GPR1, GPH1P) | 1800 | 6000 | 3000 | 10000 | 3500 | 12000 |
| 360° prism (GRZ4, GRZ122) | 800 | 2600 | 1500 | 5000 | 2000 | 7000 |
| 360° Mini prism (GRZ101) | 450 | 1500 | 800 | 2600 | 1000 | 3300 |
| Mini prism (GMP101) | 800 | 2600 | 1200 | 4000 | 2000 | 7000 |
| Reflector tape (GZM31) 60 mm x 60 mm | 150 | 500 | 250 | 800 | 250 | 800 |
| Machine Automation power prism (MPR122)  For Machine Control purposes only! | 800 | 2600 | 1500 | 5000 | 2000 | 7000 |

Shortest measuring distance: 1.5 m

For MS60 - R2000:

| Reflector | Range A | | Range B | | Range C | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|------|---------|-------|---------|--------|
| | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| Standard prism (GPR1, GPH1P) | 2200 | 7300 | 7500 | 24600 | >10000 | >32800 |
| 360° prism (GRZ4, GRZ122) | 1200 | 4000 | 2250 | 7500 | 3000 | 10500 |
| 360° Mini prism (GRZ101) | 670 | 2250 | 1200 | 3900 | 1500 | 5000 |
| Mini prism (GMP101) | 1200 | 4000 | 1800 | 6000 | 3000 | 10500 |
| Reflector tape (GZM31) 60 mm x 60 mm | 220 | 750 | 375 | 1200 | 370 | 1200 |
| Machine Automation power prism (MPR122)  For Machine Control purposes only! | 1200 | 4000 | 2250 | 7500 | 3000 | 10500 |

Shortest measuring distance: 1.5 m

Atmospheric conditions

Range A: Strong haze, visibility 5 km; or strong sunlight, severe heat shimmer
Range B: Light haze, visibility about 20 km; or moderate sunlight, slight heat shimmer
Range C: Overcast, no haze, visibility about 40 km; no heat shimmer



Measurements can be made to reflector tapes over the entire range without external ancillary optics.

Accuracy

Accuracy refers to measurements to standard prisms.

For TS60 - R1000:

| Distance measuring mode | std. dev. ISO 17123-4, standard prism | std. dev. ISO 17123-4, tape** | Measurement time, typical [s] |
|-------------------------|---------------------------------------|-------------------------------|-------------------------------|
| Precise | 0.6 mm + 1 ppm* | 1 mm + 1 ppm | 7 |
| Standard | 1 mm + 1 ppm | 1 mm + 1 ppm | 2.4 |
| Fast | 2 mm + 1 ppm | 3 mm + 1 ppm | 2.0 |
| Continuously | 3 mm + 1 ppm | 3 mm + 1 ppm | < 0.15 |
| Averaging | 1 mm + 1 ppm | 1 mm + 1 ppm | - |

Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy.

* Atmospheric conditions type C, range up to 1000 m, GPH1P reflector

** Target aligned to instrument

For MS60 - R2000:

| Distance measuring mode | std. dev. ISO 17123-4, standard prism | std. dev. ISO 17123-4, tape* | Measurement time, typical [s] |
|-------------------------|---------------------------------------|------------------------------|-------------------------------|
| Standard | 1 mm + 1.5 ppm | 1 mm + 1.5 ppm | 1.5 |
| Fast | 2 mm + 1.5 ppm | 3 mm + 1.5 ppm | 1.0 |
| Continuously | 2 mm + 1.5 ppm | 3 mm + 1.5 ppm | >0.05** |
| Averaging | 1 mm + 1.5 ppm | 1 mm + 1.5 ppm | - |

Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy.

* Target aligned to instrument

** Auto point application increases the measurement time

Characteristics

Type: Coaxial, visible red laser
Carrier wave: 658 nm
Measuring system: R1000: System Analyzer Basis 100 MHz - 150 MHz
R2000: Wave Form Digitizer

7.3

Distance Measurement without Reflectors

Range

| Type | Kodak Gray Card | Range D | | Range E | | Range F | |
|-------|-----------------------------|---------|------|---------|------|---------|-------|
| | | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| R1000 | White side, 90 % reflective | 800 | 2630 | 1000 | 3280 | >1000 | >3280 |
| R1000 | Grey side, 18 % reflective | 400 | 1320 | 500 | 1640 | >500 | >1640 |
| R2000 | White side, 90 % reflective | 1500 | 4920 | 2000 | 6560 | >2000 | >6560 |
| R2000 | Grey side, 18 % reflective | 750 | 2460 | 1000 | 3280 | >1000 | >3280 |

Range of measurement:

R1000: 1.5 m - 1200 m

R2000: 1.5 m - 2400 m

Distance measurements below 1.5 m are not possible.

Atmospheric conditions

D: Object in strong sunlight, severe heat shimmer

E: Object in shade, sky overcast

F: Underground, night and twilight

Accuracy

For TS60 - R1000:

| Standard measuring | std. dev. ISO 17123-4 | Measure time, typical [s] | Measure time, maximum [s] |
|--------------------|-----------------------|---------------------------|---------------------------|
| 0 m - 500 m | 2 mm + 2 ppm | 3 | 12 |
| >500 m | 4 mm + 2 ppm | 6 | 12 |

Object in shade, sky overcast. Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy. The display resolution is 0.1 mm.

For MS60 - R2000:

| Standard measuring | std. dev. ISO 17123-4 | Measure time, typical [s] | Measure time, maximum [s] |
|--------------------|-----------------------|---------------------------|---------------------------|
| 0 m - 500 m | 2 mm + 2 ppm | 1.5 | 14 |
| >500 m | 4 mm + 2 ppm | 4 | 14 |

Object in shade, sky overcast. Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy. The display resolution is 0.1 mm.

* Auto point application increases the measurement time

Characteristics

Type: Coaxial, visible red laser

Carrier wave: 658 nm

Measuring system: R1000: System Analyzer Basis 100 MHz - 150 MHz

R2000: Wave Form Digitizer

Laser dot size

| Distance [m] | Laser dot size, approximately [mm] |
|--------------|------------------------------------|
| at 30 | 7 x 10 |
| at 50 | 8 x 20 |
| at 100 | 16 x 25 |

7.4**Distance Measurement - Long Range (LO mode)****Availability**

Only available for TS60.

Range

| Reflector | Range A | | Range B | | Range C | |
|------------------------------|---------|------|---------|-------|---------|--------|
| | [m] | [ft] | [m] | [ft] | [m] | [ft] |
| Standard prism (GPR1, GPH1P) | 2200 | 7300 | 7500 | 24600 | >10000 | >32800 |

Range of measurement:

1000 m to 12000 m

Display unambiguous:

up to 12000 m

Atmospheric conditions

Range A: Strong haze, visibility 5 km; or strong sunlight, severe heat shimmer

Range B: Light haze, visibility about 20 km; or moderate sunlight, slight heat shimmer

Range C: Overcast, no haze, visibility about 40 km; no heat shimmer

Accuracy

| Standard measuring | std. dev. ISO 17123-4 | Measure time, typical [s] | Measure time, maximum [s] |
|--------------------|-----------------------|---------------------------|---------------------------|
| Long Range | 3 mm + 1 ppm | 2.5 | 12 |

Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified accuracy. The display resolution is 0.1 mm.

Characteristics

Principle: Phase measurement

Type: Coaxial, visible red laser

Carrier wave: 658 nm

Measuring system: System analyser basis 100 MHz - 150 MHz

7.5

Automatic Target Aiming (ATRplus)

Range of Target Aiming/ Target Locking

For MS60/TS60:

| Prism | Range (Target Aiming) | | Range (Target Locking) | |
|---------------------------------------------------------------------------------|-----------------------|------|------------------------|------|
| | [m] | [ft] | [m] | [ft] |
| Standard prism (GPR1) | 1500 | 5000 | 1000 | 3300 |
| 360° prism (GRZ4, GRZ122) | 1000 | 3300 | 1000 | 3300 |
| 360° Mini prism (GRZ101) | 450 | 1500 | 250 | 830 |
| Mini prism (GMP101) | 900 | 3000 | 600 | 2000 |
| Reflector tape (GZM31) 60 mm x 60 mm | 55 | 190 | not qualified | |
| Machine Automation power prism (MPR122) ☞ For Machine Control purposes only! | 750 | 2500 | 650 | 2200 |
| ☞ The maximum range can be restricted by poorer conditions, for example rain. | | | | |

Shortest measuring distance: 360° prism (Target aiming): 1.5 m

Shortest measuring distance: 360° prism (Target locking): 5 m

ATRplus Accuracy with the GPR1 Prism

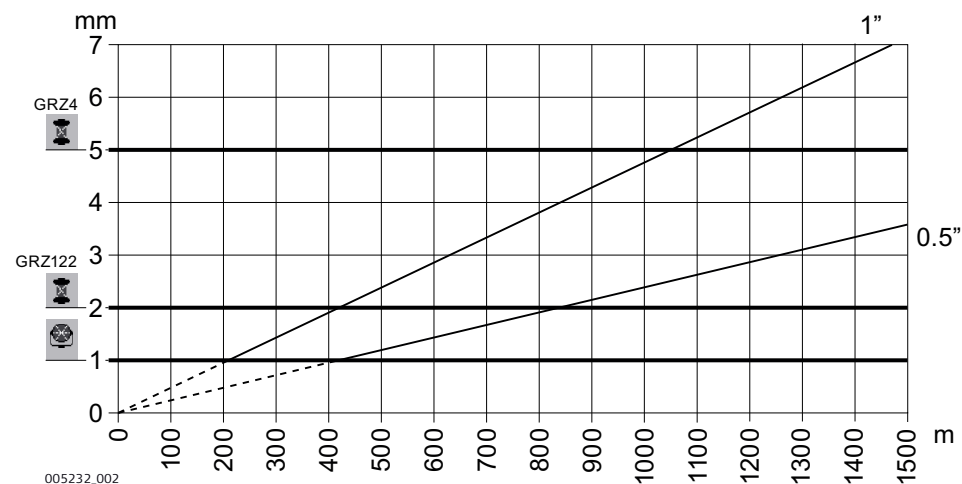
ATRplus angle accuracy Hz, V (std. dev. ISO 17123-3, atmospheric conditions type C):

TS60, 0.5": 0.5 " (0.15 mgon)

MS60, 1": 1 " (0.3 mgon)

Measurement Accuracy with ATRplus

- The accuracy with which the position of a prism can be determined with Automatic Target Aiming (ATRplus) depends on several factors such as internal ATRplus accuracy, instrument angle accuracy, prism type, selected EDM measuring program and the external measuring conditions. The ATRplus has a basic standard deviation level of ± 1 mm for 1" instruments and ± 0.5 mm for 0.5" instruments.
- The following graph shows the typical ATRplus measurement accuracies based on three different prism types, distances and instrument accuracies.



Leica GRZ4 prism (360°)

Leica GRZ122 prism (360°)

Leica circular prisms and Leica circular Mini prisms

| | |
|----|-------------------------------|
| mm | ATRplus accuracy [mm] |
| m | Distance measurement [m] |
| " | Instrument angle accuracy ["] |

| | | |
|-----------------------------------|-----------------------------------------------------------------|-----------------------------------|
| Maximum Speed in Lock Mode | Maximum tangential speed: | 9 m/s at 20 m; 45 m/s at 100 m |
| | Maximum radial speed with Measure distance: Continuously | 5 m/s for TS60 14 m/s for MS60 |

| | | |
|------------------|---------------------------------------|----------------|
| Searching | Typical search time in field of view: | 1.5 s |
| | Field of view: | 1°25'/1.55 gon |
| | Definable search window: | Yes |

| | | |
|------------------------|------------|--------------------------|
| Characteristics | Principle: | Digital image processing |
| | Type: | Infrared laser |

7.6 Scanning

Availability Available for MS60 R2000 and on CS when connected to MS60 R2000.

Range The following ranges refer to optimal measurement conditions (object in shade, sky overcast, static target object).

| Mode | Kodak Grey Card (Albedo 90%) | Range, up to | |
|---------|------------------------------|--------------|------|
| | | [m] | [ft] |
| 1000 Hz | White side, 90% Albedo | 300 | 980 |
| 250 Hz | | 400 | 1310 |
| 62 Hz | | 500 | 1640 |
| >1 Hz | | 1000 | 3280 |

Shortest measuring distance: 1.5 m

Accuracy Range noise* (1 sigma; Kodak Grey Card (Albedo 90%)):

| Distance | 1000 Hz | 250 Hz | 62 Hz | 1 Hz |
|----------|---------|--------|--------|--------|
| 10 m | 0.6 mm | 0.5 mm | 0.4 mm | 0.4 mm |
| 25 m | 0.8 mm | 0.6 mm | 0.5 mm | 0.5 mm |
| 50 m | 1.0 mm | 0.8 mm | 0.6 mm | 0.6 mm |
| 100 m | 2.0 mm | 1.0 mm | 0.8 mm | 0.8 mm |
| 200 m | 6.0 mm | 3.0 mm | 2.0 mm | 1.8 mm |

Object in shade, sky overcast. Beam interruptions, severe heat shimmer and moving objects within the beam path can result in deviations of the specified range noise and accuracy.

- * Range noise describes the standard deviation of the scan points residuals to the modelled surface:
- Plane surface target
 - Perpendicular orientation of the plane target to the measurement direction
 - Modelled plane best fitted into the point cloud


The absolute position accuracy of a modelled surface is similar to an RL single measurement:

| Standard measuring | std. dev. ISO 17123-4 |
|--------------------|-----------------------|
| 0 m - 500 m | 2 mm + 2 ppm |
| >500 m | 4 mm + 2 ppm |

7.7

PowerSearch PS

Range

| Reflector | Range PS | |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------|-------|
| | [m] | [ft] |
| Standard prism (GPR1) | 300 | 1000 |
| 360° prism (GRZ4, GRZ122) | 300* | 1000* |
| 360° mini prism (GRZ101) | Not recommended | |
| Mini prism (GMP101) | 100 | 330 |
| Machine Automation power prism (MPR122)  For Machine Control purposes only! | 300* | 1000* |

Measurements at the vertical limits of the fan or under unfavourable atmospheric conditions may reduce the maximum range. (*optimally aligned to the instrument)

Shortest measuring distance: 1.5 m

Searching

| | |
|---------------------------|------------------------|
| Typical search time: | 5 - 10 s |
| Rotating Speed: | up to 100 gon/s |
| Default search area: | Hz: 400 gon, V: 40 gon |
| Definable search windows: | Yes |

Characteristics

| | |
|------------|---------------------------|
| Principle: | Digital signal processing |
| Type: | Infrared laser |

7.8

Overview Camera

Overview camera

| | |
|----------------|---------------------------------------------------------------------------------------------|
| Sensor: | 5 Mpixel CMOS sensor |
| Focal length: | 21 mm |
| Field of view: | 15.5° x 11.7° (19.4° diagonal) |
| Frame rate: | ≤20 frames per second |
| Focus: | 2 m (6.6 ft) to infinity at zoom level 1 x 7.5 m (24.6 ft) to infinity at zoom level 4 x |
| Image storage: | JPEG up to 5 Mpixel (2560 x 1920) |
| Zoom: | 4-step (1x, 2x, 4x, 8x) |
| Whitebalance: | Automatic and user configurable |
| Brightness: | Automatic and user configurable |

7.9

Telescope Camera

| | | |
|-------------------------|----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Telescope camera | Sensor: | 5 Mpixel CMOS sensor |
| | Focal length: | At ∞ 231mm |
| | Field of view: | 1.5° diagonal |
| | Frame rate: | ≤20 frames per second |
| | Focus: | Servofocus: Manual motorised focus, available for all variants instrument types Autofocus: Automatic focusing, available for instruments with imaging functionality |
| | Time to focus: | Typical 2 s |
| | Focus range: | 1.7 m to infinity |
| | Image storage: | JPEG up to 5 Mpixel (2560 x 1920) |
| | Zoom, digital: | 4-step (1x, 2x, 4x, 8x) |
| | Whitebalance: | Automatic and user configurable |
| | Brightness: | Automatic and user configurable |

7.10

SmartStation

7.10.1

SmartStation Accuracy



Measurement precision and accuracy in position and accuracy in height are dependent upon various factors including the number of satellites tracked, constellation geometry, observation time, ephemeris accuracy, ionospheric disturbance, multipath and resolved ambiguities. Figures quoted assume normal to favourable conditions.

Times required are dependent upon various factors including number of satellites, geometry, ionospheric conditions, multipath and so on. GS and GLONASS can increase performance and accuracy by up to 30 % relative to GS only. A full Galileo and GS L5 constellation will further increase measurement performance and accuracy.

Accuracy

| | |
|--------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Position accuracy: | Horizontal: 10 mm + 1 ppm Vertical: 20 mm + 1 ppm When used within reference station networks the position accuracy is in accordance with the accuracy specifications provided by the reference station network. |
|--------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

Initialisation

| | |
|--------------------------------|-------------------------------------------------------|
| Method: | Real-time (RTK) |
| Reliability of initialisation: | Better than 99.99 % |
| Time of initialisation: | Typically 8 s, with 5 or more satellites on L1 and L2 |
| Range: | Up to 50 km, assuming reliable data-link is available |

RTK Data Formats

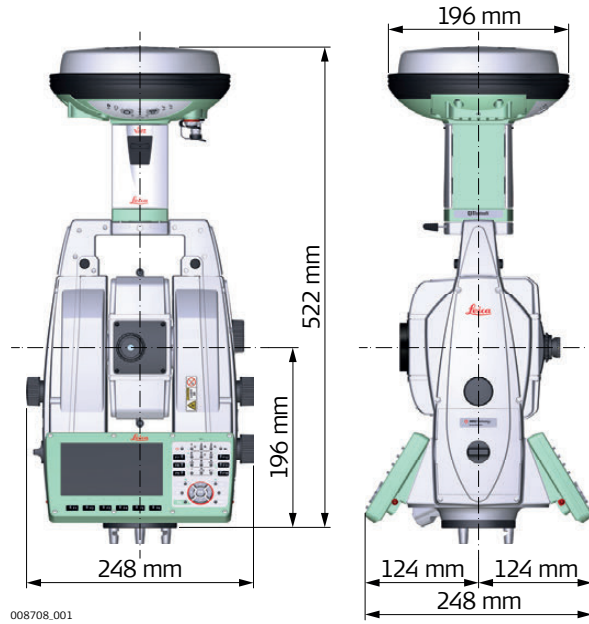
| | |
|-----------------------------|---------------------------------------------------------------------------------------------------------------|
| Formats for data reception: | Leica proprietary GPS / Glonass and GNSS real-time data formats, CMR, CMR+, RTCM V2.1 / 2.2 / 2.3 / 3.1 / 3.2 |
|-----------------------------|---------------------------------------------------------------------------------------------------------------|

7.10.2

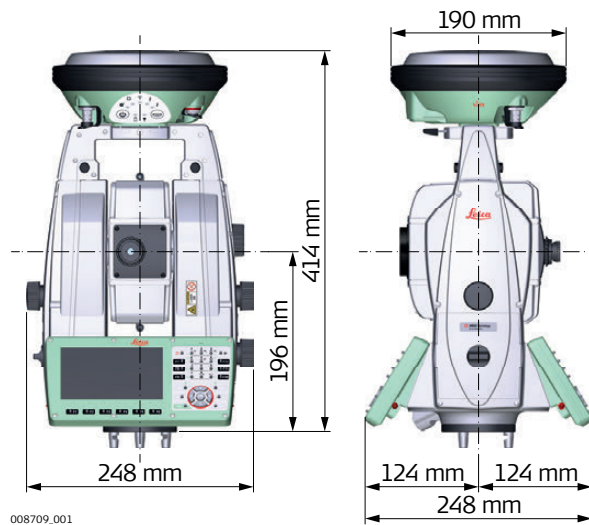
SmartStation Dimensions

SmartStation Dimensions

With GS15



With GS14



Description and Use The SmartAntenna is selected for use based upon the application. The table gives a description and the intended use of the SmartAntenna.

| Type | Description | Use |
|-----------|-----------------------------------------------------------------------------|--------------------------------------------------|
| GS14/GS15 | GPS, GLONASS, Galileo, BeiDou SmartTrack antenna with built-in groundplane. | With CS20 or Leica Viva and Nova TS instruments. |

Dimensions

| Type | Height [m] | Diameter [m] |
|------|------------|--------------|
| GS14 | 0.090 | 0.190 |
| GS15 | 0.198 | 0.196 |

Connector

- 8 pin LEMO-1 socket to connect antenna cable (only applicable when SmartAntenna is used independently on a pole with CS field controller).
- Special clip-on interface for connecting SmartAntenna to SmartAntenna Adapter on the instrument.

Mounting

5/8" Whitworth

Weight

Instrument weights without battery and radio:

| Type | Weight [kg]/[lbs] |
|------|-------------------|
| GS14 | 0.93/2.04 |
| GS15 | 1.34/2.95 |

Power

Power consumption:

- GS14, radio excluded: 2.0 W typically, 166 mA with external battery, 270 mA with internal battery
- GS15, radio excluded: 3.2 W typically

External supply voltage: Nominal 12 V DC (---, GEV197 SmartAntenna to PC for data transfer and to external power supply), voltage range 10.5-28 V DC

Internal Battery

Type: Li-Ion
 Voltage: 7.4 V
 Capacity: GEB212: 2.6 Ah
 Typical operating time: GEB212: 6.5 h

Electrical Data

| Type | GS14 | GS15 |
|---------------------------------|------|------|
| Frequency | | |
| GS L1 1575.42 MHz | ✓ | ✓ |
| GS L2 1227.60 MHz | ✓ | ✓ |
| GS L5 1176.45 MHz | - | ✓ |
| GLONASS L1 1602.5625-1611.5 MHz | ✓ | ✓ |
| GLONASS L2 1246.4375-1254.3 MHz | ✓ | ✓ |
| Galileo E1 1575.42 MHz | ✓ | ✓ |
| Galileo E5a 1176.45 MHz | - | ✓ |
| Galileo E5b 1207.14 MHz | ✓ | ✓ |

| Type | GS14 | GS15 |
|------------------------------|---------|-------------------|
| Galileo Alt-BOC 1191.795 MHz | - | ✓ |
| BeiDou B1 1561.098 MHz | ✓ | ✓ |
| BeiDou B2 1207.14 MHz | ✓ | ✓ |
| Gain | 27 dBi | Typically 27 dBi |
| Noise Figure | < 2 dBi | Typically < 2 dBi |



Environmental Specifications

Galileo Alt-BOC covers bandwidth of Galileo E5a and E5b.

Temperature

| Operating temperature [°C] | Storage temperature [°C] |
|----------------------------|--------------------------|
| -40 to +65 | -40 to +80 |
| Bluetooth: -30 to +65 | |

Protection against water, dust and sand

| Protection | |
|-------------------------------------------------|-------------------------------------------------|
| GS15 | GS14 |
| IP68 (IEC 60529) | IP68 (IEC 60529) |
| Dust tight | Dust tight |
| Protected against continuous immersion in water | Protected against continuous immersion in water |
| Tested for 2 hours in 1.40 m depth | Tested for 2 hours in 1.40 m depth |

Humidity

| Protection |
|--------------------------------------------------------------------------------------------------------|
| Up to 100 % |
| The effects of condensation are to be effectively counteracted by periodically drying out the antenna. |

7.11

7.11.1

Conformity to National Regulations

MS60/TS60

Conformity to national regulations

- FCC Part 15 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the product MS60/TS60 is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC and other applicable European Directives. The declaration of conformity may be consulted at <http://www.leica-geosystems.com/ce>.



Class 1 equipment according European Directive 1999/5/EC (R&TTE) can be placed on the market and be put into service without restrictions in any EU Member state.

- The conformity for countries with other national regulations not covered by the FCC part 15 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance.
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency band

| Type | Frequency band [MHz] |
|-----------|--------------------------------|
| Bluetooth | 2402 - 2480 |
| WLAN | 2400 - 2483, channel 1-11 only |

Output Power

| Type | Output power [mW] |
|----------------|-------------------|
| Bluetooth | < 15 |
| WLAN (802.11b) | 100 |
| WLAN (802.11g) | 60 |

Antenna

| Type | Antenna | Gain [dBi] | Connector | Frequency band [MHz] |
|-----------|--------------------|------------|-----------|----------------------|
| Bluetooth | Integrated antenna | - | - | - |
| WLAN | Integrated antenna | - | - | - |

7.11.2**RadioHandle****Conformity to national regulations**

- FCC Part 15 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the RadioHandle is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC and other applicable European Directives. The declaration of conformity may be consulted at <http://www.leica-geosystems.com/ce>.



Class 1 equipment according European Directive 1999/5/EC (R&TTE) can be placed on the market and be put into service without restrictions in any EEA Member state.

- The conformity for countries with other national regulations not covered by the FCC part 15 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance.
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency Band

| | |
|------|----------------------------|
| RH16 | Limited to 2402 - 2480 MHz |
| RH17 | Limited to 2402 - 2480 MHz |

Output power

< 100 mW (e. i. r. p.)

Antenna

| | |
|------------|----------------------------|
| Type: | $\lambda/2$ dipole antenna |
| Gain: | 2 dBi |
| Connector: | Special customized SMB |

Conformity to national regulations

- FCC Part 15 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the product GS14 is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC and other applicable European Directives. The declaration of conformity can be consulted at <http://www.leica-geosystems.com/ce>.



Class 2 equipment according European Directive 1999/5/EC (R&TTE)

- The conformity for countries with other national regulations not covered by the FCC part 15 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance (applicable for Japan).
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency band

| Type | Frequency band [MHz] |
|---------------------------|------------------------------------------------------------------|
| GS14 | 1227.60 1246.4375 - 1254.3 1575.42 1602.5625 - 1611.5 |
| GS14, Bluetooth | 2402 - 2480 |
| GS14, Radio | 403 - 473 |
| GS14, 2G GSM | Quad-Band EGSM 850 / 900 / 1800 / 1900 |
| GS14, 3.75G GSM/UMTS | Quad-Band GSM & Penta-Band UMTS 800 / 850 / 900 / 1900 / 2100 |
| GS14, 3.75G GSM/UMTS/CDMA | Quad-Band GSM & Penta-Band UMTS & Tri-Band CDMA 800 / 1900 |

Output power

| Type | Output power [mW] |
|-------------------------------------|----------------------------------------------|
| GNSS | Receive only |
| Bluetooth | 5 |
| Radio | 1000 |
| 2G GSM EGSM850/900 | 2000 |
| 2G GSM GSM1800/1900 | 1000 |
| 2G GSM | GPRS multi-slot class 10 (max. 2/8 TX) |
| 3.75G GSM | E(dge)GPRS multi-slot class 12 (max. 4/8 TX) |
| 3.75G UMTS 800/850/900/1900/2100 | 250 |
| CDMA BC0 & BC10 (800)/BC1 (1900) | 250 |

Antenna

| Type | Antenna | Gain [dBi] |
|---------------|----------------------------------------------|---------------------------------------------------------|
| GNSS | Internal GNSS antenna element (receive only) | - |
| Bluetooth | Internal Microstrip antenna | 2 max. |
| UHF | External antenna | - |
| GSM/UMTS/CDMA | Integrated antenna | 0 max. @ 800 / 850 / 900 3 max. @ 1800 / 1900 / 2100 |

7.11.4

GS15

Conformity to national regulations

- FCC Part 15, 22 and 24 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the product GS15 is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC. The declaration of conformity can be consulted at <http://www.leica-geosystems.com/ce>.



Class 1 equipment according European Directive 1999/5/EC (R&TTE) can be placed on the market and be put into service without restrictions in any EEA member state.

- The conformity for countries with other national regulations not covered by the FCC part 15, 22 and 24 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance (applicable for Japan).
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency band

| Type | Frequency band [MHz] |
|-----------|--------------------------------------------------------------------------------------------------------------|
| GS15 | 1176.45 1191.795 1207.14 1227.60 1246.4375 - 1254.3 1561.098 1575.42 1602.4375 - 1611.5 |
| Bluetooth | 2402 - 2480 |

Output power

| Type | Output power [mW] |
|-----------|-------------------|
| GNSS | Receive only |
| Bluetooth | 5 (Class 1) |

Antenna

| Type | Antenna | Gain [dBi] | Connector | Frequency band [MHz] |
|-----------|----------------------------------------------|------------|-----------|----------------------|
| GNSS | Internal GNSS antenna element (receive only) | - | - | - |
| Bluetooth | Internal Microstrip antenna | 1.5 | - | - |

7.11.5

SLR5, SATEL SATELLINE M3-TR1

Conformity to National Regulations

- FCC Part 15 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the product SLR5 is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC and other applicable European Directives. The declaration of conformity can be consulted at <http://www.leica-geosystems.com/ce>.



Class 2 equipment according European Directive 1999/5/EC (R&TTE)

- The conformity for countries with other national regulations not covered by the FCC part 15 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance.
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency band

403 MHz - 470 MHz

Output power

SLR5: 0.5 W-1.0 W

Antenna

| Type | Internal | GAT_1 | GAT_2 |
|----------------------|-----------|--------------------------------|--------------------------------|
| Frequency band [MHz] | 400 - 470 | 400 - 435 | 435 - 470 |
| Type | Internal | Detachable $\lambda/2$ antenna | Detachable $\lambda/2$ antenna |
| Connector | - | TNC | TNC |

Specific Absorption Rate (SAR)

The product meets the limits for the maximum permissible exposure of the guide-lines and standards which are force in this respect. The product must be used with the recommended antenna. A separation distance of at least 20 centimetres should be kept between the antenna and the body of the user or nearby person within the intended application.

7.11.6

SLG1, Telit UC864-G

Conformity to national regulations

- FCC Part 15, 22 and 24 (applicable in US)
- Hereby, Leica Geosystems AG, declares that the SLG1 is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC and other applicable European Directives. The declaration of conformity may be consulted at <http://www.leica-geosystems.com/ce>.



Class 1 equipment according European Directive 1999/5/EC (R&TTE) can be placed on the market and be put into service without restrictions in any EEA Member state.

- The conformity for countries with other national regulations not covered by the FCC part 15, 22 and 24 or European directive 1999/5/EC has to be approved prior to use and operation.
- Japanese Radio Law and Japanese Telecommunications Business Law Compliance.
 - This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
 - This device should not be modified (otherwise the granted designation number will become invalid).

Frequency band UMTS/HSDPA (WCDMA/FDD) 850 MHz/ 1900 MHz/ 2100 MHz
 Quad-Band EGSM 850 MHz/ 900 MHz/ 1800 MHz/ 1900 MHz
 GPRS multi-slot class 12
 EDGE multi-slot class 12

Output power

| | |
|----------------|--------|
| EGSM850/900: | 2 W |
| GSM1800/1900: | 1 W |
| UMTS2100: | 0.25 W |
| EDGE850/900: | 0.5 W |
| EDGE1800/1900: | 0.4 W |

Antenna

| Type | GS15 Internal | GAT_3 | GAT_5 | GAT_18 |
|----------------------|-----------------------------------------------------------------------------|---------------------------------------------|--------------------------------|-----------------------------------------------------------------------------|
| Frequency band [MHz] | 824 - 894 / 890 - 960 / 1710 - 1880 / 1850 - 1990 / 1920 - 2170 | 890 - 960 / 1710 - 1880 / 1920 - 2170 | 824 - 894 / 1850 - 1990 | 824 - 894 / 890 - 960 / 1710 - 1880 / 1850 - 1990 / 1920 - 2170 |
| Type | Internal | Detachable $\lambda/2$ antenna | Detachable $\lambda/2$ antenna | Detachable $\lambda/2$ antenna |
| Connector | - | TNC | TNC | TNC |




Specific Absorption Rate (SAR) The product meets the limits for the maximum permissible exposure of the guide-lines and standards which are force in this respect. The product must be used with the recommended antenna. A separation distance of at least 20 centimetres should be kept between the antenna and the body of the user or nearby person within the intended application.

7.11.7 Dangerous Goods Regulations

Dangerous Goods Regulations

The products of Leica Geosystems are powered by Lithium batteries.

Lithium batteries can be dangerous under certain conditions and can pose a safety hazard. In certain conditions, Lithium batteries can overheat and ignite.

-  When carrying or shipping your Leica product with Lithium batteries onboard a commercial aircraft, you must do so in accordance with the **IATA Dangerous Goods Regulations**.
-  Leica Geosystems has developed **Guidelines** on "How to carry Leica products" and "How to ship Leica products" with Lithium batteries. Before any transportation of a Leica product, we ask you to consult these guidelines on our web page (<http://www.leica-geosystems.com/dgr>) to ensure that you are in accordance with the IATA Dangerous Goods Regulations and that the Leica products can be transported correctly.
-  Damaged or defective batteries are prohibited from being carried or transported onboard any aircraft. Therefore, ensure that the condition of any battery is safe for transportation.

7.12

General Technical Data of the Instrument

| | | |
|------------------|---------------------------|-----------------------------------|
| Telescope | Magnification: | 30 x |
| | Clear objective diameter: | 40 mm |
| | Focusing: | 1.7 m/5.6 ft to infinity |
| | Field of view: | 1°30'/1.66 gon. 2.7 m at 100 m |

Compensator

| Type | Setting accuracy | | Setting range | |
|-----------|------------------|--------|---------------|-------|
| | ["] | [mgon] | ['] | [gon] |
| All types | 0.5 | 0.15 | 4 | 0.07 |

Level

| | |
|------------------------------|-----------------------------------------|
| Compensation: | Centralised quadruple axis compensation |
| Circular level sensitivity: | 6'/2 mm |
| Electronic level resolution: | 2" |

Control Unit

| | |
|-------------------|-----------------------------------------------------------------------------------|
| Display: | WVGA (800 x 480 pixels), colour, graphics capable LCD, illumination, touch screen |
| Keyboard: | 37 keys including 12 function keys and 12 alphanumeric keys, illumination |
| Angle Display: | 360°", 360° decimal, 400 gon, 6400 mil, V % |
| Distance Display: | m, ft int, ft us, ft int inch, ft us inch |
| Position: | TS60/MS60 both faces |
| Touch screen: | Screen protection foil on glass |

Instrument Ports

| Name | Description |
|---------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Serial/USB | <ul style="list-style-type: none"> 8 pin LEMO-1 for power, communication, data transfer. This port is located at the base of the instrument. |
| RadioHandle | <ul style="list-style-type: none"> Hotshoe connection for RadioHandle with Remote Mode and SmartAntenna Adapter with SmartStation. This port is located on top of the Communication side cover. |
| Bluetooth | <ul style="list-style-type: none"> Bluetooth module for communication. This port is housed within the Communication side cover. |
| WLAN | <ul style="list-style-type: none"> WLAN module for communication. This port is housed within the Communication side cover. |
| USB host port | <ul style="list-style-type: none"> USB memory stick port for data transfer. |

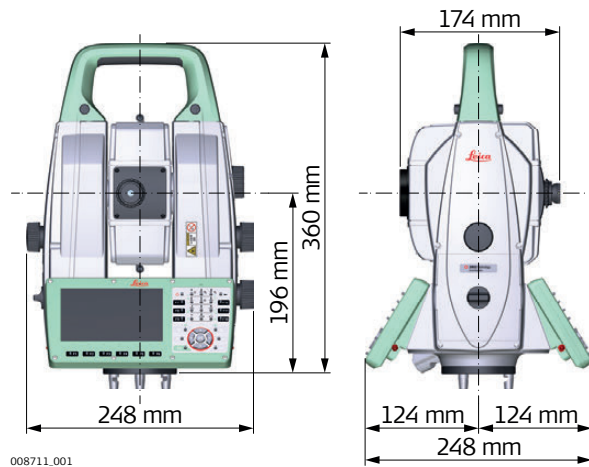
Pin Assignments of the 8 Pin LEMO-1 Port



008364.001

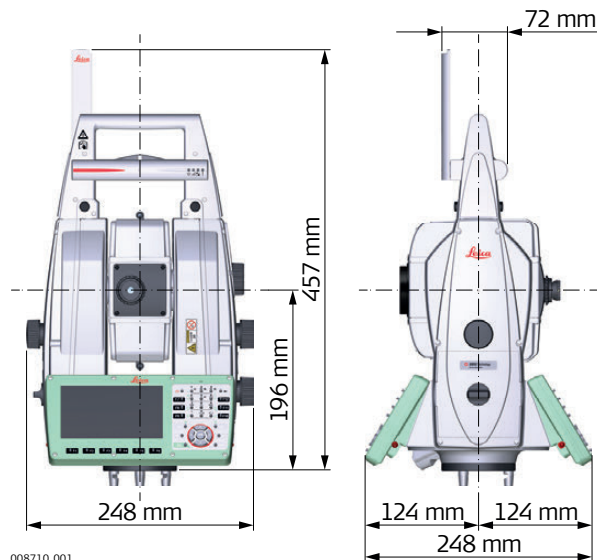
- a) Pin 1: USB data line (In or out)
- b) Pin 2: USB data line (In or out)
- c) Pin 3: Signal ground
- d) Pin 4: RxD (RS232, receive data, In)
- e) Pin 5: TxD (RS232, transmit data, Out)
- f) Pin 6: Identification pin (In or out)
- g) Pin 7: Power input, nominal +12 V (11 V - 16 V, In)
- h) Pin 8: Not connected

Instrument Dimensions



008711.001

With RH16/RH17



008710.001

| | | |
|---------------|-------------------|---------|
| Weight | Instrument: | 7.27 kg |
| | Tribrach: | 0.8 kg |
| | Internal battery: | 0.43 kg |

Recording Data can be recorded onto an SD card or into internal memory.

| Type | Capacity [MB] | Number of measurements per MB |
|-----------------|--------------------------------------------------------------------------|-------------------------------|
| SD card | <ul style="list-style-type: none"> • 1024 • 8192 | 1750 |
| Internal memory | <ul style="list-style-type: none"> • 2048 | 1750 |

| | | |
|----------------------|-----------|---------------------------------------------------------------------------------------------------------------------------------|
| Laser Plummet | Type: | Visible red laser class 2 |
| | Location: | In standing axis of instrument |
| | Accuracy: | Deviation from plumbline: 1.5 mm at 1.5 m instrument height Diameter of laser point: 2.5 mm at 1.5 m instrument height |

| | | |
|------------------|------------------------|------------------------------------------------------------------|
| Operation | Three endless drives: | For one and two hand manual operation |
| | User defined Smartkey: | Fast precision triggerkey for manual high precision measurements |

| | | |
|---------------------|-------------------------|------------------------|
| Motorisation | Maximum acceleration: | 400 gon/s ² |
| | Maximum rotating speed: | 200 gon/s |
| | Time for change face: | Typically 2.9 s |

| | | |
|--------------|------------------------------|----------------------------------------------|
| Power | External supply voltage: | Nominal voltage 12.8 V DC Range 12 V-18 V |
| | Standby power consumption: | Typically 0.3 W |
| | Operating power consumption: | Typically 12 W (max. 40 W) |

| | | |
|-------------------------|-----------|----------------|
| Internal Battery | Type: | Li-Ion |
| | Voltage: | 14.8 V |
| | Capacity: | GEB242: 5.8 Ah |

| | | |
|-------------------------|-----------|---------------|
| External Battery | Type: | Li-Ion |
| | Voltage: | 13 V |
| | Capacity: | GEB371: 19 Ah |

Environmental Specifications

Temperature

| Type | Operating temperature [°C] | Storage temperature [°C] |
|---------------------------|----------------------------|--------------------------|
| All types | -20 to +50 | -40 to +70 |
| Leica SD cards, all sizes | -40 to +80 | -40 to +80 |
| Battery internal | -20 to +55 | -40 to +70 |


Protection against water, dust and sand

| Type | Protection |
|-----------|------------------|
| All types | IP65 (IEC 60529) |

Humidity

| Type | Protection |
|-----------|--------------------------------------------------------------------------------------------------------------------------------------|
| All types | Max 95 % non condensing The effects of condensation are to be effectively counteracted by periodically drying out the instrument. |

Reflectors

| Type | Additive Constant [mm] | ATRplus | PS |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------|---------|-----------------|
| Standard prism, GPR1 | 0.0 | yes | yes |
| Mini prism, GMP101 | +17.5 | yes | yes |
| 360° prism, GRZ4 / GRZ122 | +23.1 | yes | yes |
| 360° Mini prism, GRZ101 | +30.0 | yes | not recommended |
| Reflector tape S, M, L | +34.4 | yes | no |
| Reflectorless | +34.4 | no | no |
| Machine Automation power prism, MPR122  For Machine Control purposes only! | +28.1 | yes | yes |

There are no special prisms required for ATRplus or for PS.

Electronic Guide Light EGL

| | |
|--------------------|---------------------------------|
| Working range: | 5 m to 150 m (15 ft to 500 ft) |
| Position accuracy: | 5 cm at 100 m (1.97" at 330 ft) |

Automatic Corrections

The following automatic corrections are made:

- Line of sight error
- Tilting axis error
- Earth curvature
- Circle eccentricity
- Compensator index error
- Vertical index error
- Standing axis tilt
- Refraction
- ATRplus zero point error
- Telescope camera zero point error

7.13

Scale Correction

Use of scale correction

By entering a scale correction, reductions proportional to distance can be taken into account.

- Atmospheric correction.
- Reduction to mean sea level.
- Projection distortion.

Atmospheric correction $\Delta D1$

The slope distance displayed is correct if the scale correction in ppm, mm/km, which has been entered corresponds to the atmospheric conditions prevailing at the time of the measurement.

The atmospheric correction includes:

- Adjustments for air pressure
- Air temperature
- Relative humidity

For highest precision distance measurements, the atmospheric correction should be determined with an accuracy of 1 ppm. The following parameters must be redetermined:

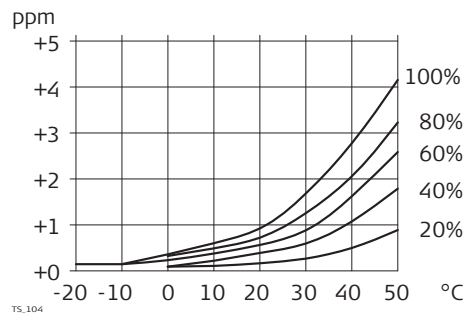
- Air temperature to 1 °C
- Air pressure to 3 mbar
- Relative humidity to 20 %

Air humidity

The air humidity influences the distance measurement if the climate is extremely hot and damp.

For high precision measurements, the relative humidity must be measured and entered along with the air pressure and the temperature.

Air humidity correction



ppm Air humidity correction [mm/km]
 % Relative humidity [%]
 °C Air temperature [°C]

Index n

| Type | Index n | Carrier wave [nm] |
|-----------------------------------------------------------------|-----------|-------------------|
| MS60 with R2000 (Wave Form Digitizer) | 1.0002863 | 658 |
| TS60 with R1000 Combined EDM (Phase Shift / System Analyzer) | | |

The index n is calculated from the formula of the IAG Resolutions (1999), and is valid for:

Air pressure p: 1013.25 mbar
 Air temperature t: 12 °C
 Relative air humidity h: 60 %

Formulas

Formula for visible red laser

$$\Delta D_1 = 286.338 - \left[\frac{0.29535 \cdot p}{(1 + \alpha \cdot t)} - \frac{4.126 \cdot 10^{-4} \cdot h}{(1 + \alpha \cdot t)} \cdot 10^x \right]$$

002419_002

ΔD_1 Atmospheric correction [ppm]

p Air pressure [mbar]

t Air temperature [°C]

h Relative humidity [%]

$\alpha = \frac{1}{273.15}$

x $(7.5 \cdot t / (237.3 + t)) + 0.7857$

If the basic value of 60 % relative humidity as used by the EDM is retained, the maximum possible error in the calculated atmospheric correction is 2 ppm, 2 mm/km.

Reduction to mean sea level ΔD_2

The values for ΔD_2 are always negative and are derived from the following formula:

$$\Delta D_2 = - \frac{H}{R} \cdot 10^6$$

TS_106

ΔD_2 Reduction to mean sea level [ppm]
 H Height of EDM above sea level [m]
 R $6.378 \cdot 10^6$ m

Projection distortion ΔD_3

The magnitude of the projection distortion is in accordance with the projection system used in a particular country, for which official tables are generally available. The following formula is valid for cylindrical projections such as that of Gauss-Krüger:

$$\Delta D_3 = \frac{X^2}{2R^2} \cdot 10^6$$

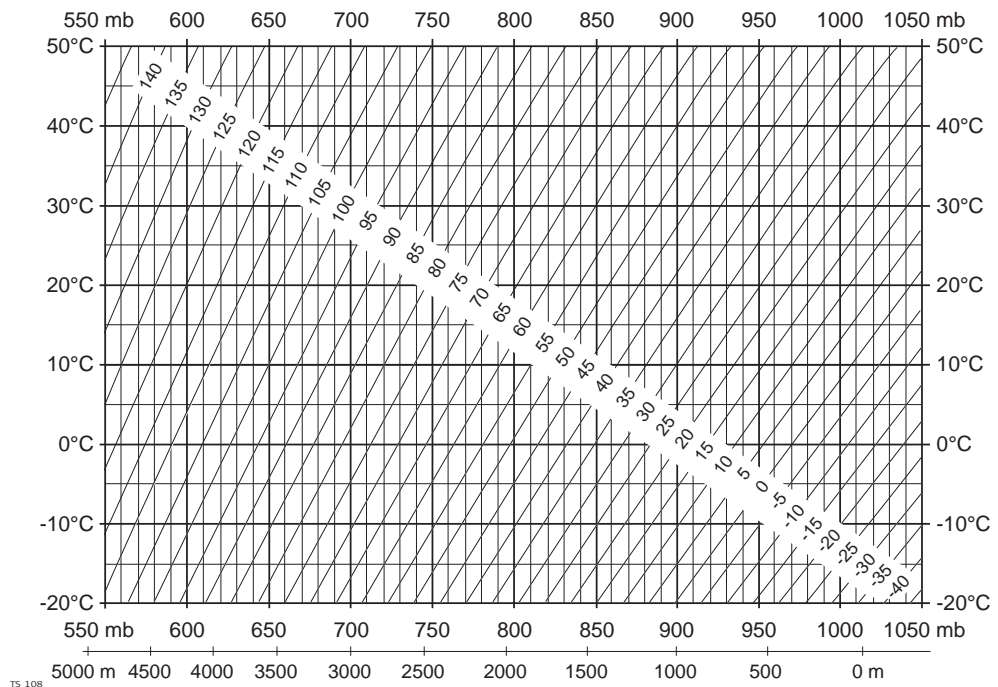
TS_107

ΔD_3 Projection distortion [ppm]
 X Easting, distance from projection zero line with the scale factor 1 [km]
 R $6.378 \cdot 10^6$ m

In countries where the scale factor is not unity, this formula cannot be directly applied.

Atmospheric corrections $^{\circ}\text{C}$

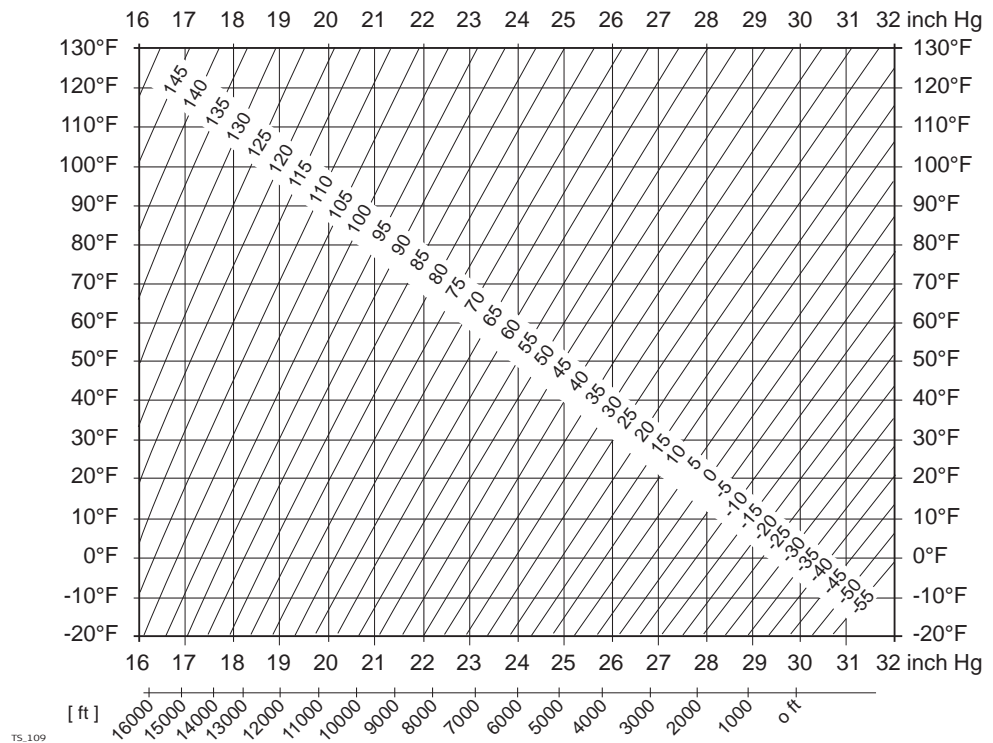
Atmospheric corrections in ppm with temperature [$^{\circ}\text{C}$], air pressure [mb] and height [m] at 60 % relative humidity.



TS_108

Atmospheric correction °F

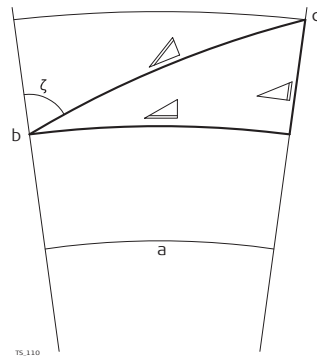
Atmospheric corrections in ppm with temperature [°F], air pressure [inch Hg] and height [ft] at 60 % relative humidity.



7.14

Reduction Formulas

Measurements



- a) Mean Sea Level
- b) Instrument
- c) Reflector
- Slope distance
- Horizontal distance
- Height difference

Reflector types

The reduction formulas are valid for measurements to all reflector types:

- measurements to prisms, to reflector tape and reflectorless measurements.

Formulas

The instrument calculates the slope distance, horizontal distance, height difference in accordance with the following formulas:

$$\triangle = D_0 \cdot (1 + \text{ppm} \cdot 10^{-6}) + \text{mm}$$

TS.111

- Displayed slope distance [m]
- D_0 Uncorrected distance [m]
- ppm Atmospheric scale correction [mm/km]
- mm Additive constant of the reflector [mm]

$$\triangle = Y - A \cdot X \cdot Y$$

TS.112

$$\triangle = X + B \cdot Y^2$$

TS.113

\triangle Horizontal distance [m]

\triangle Height difference [m]

Y $\triangle * |\sin\zeta|$

X $\triangle * \cos\zeta$

ζ Vertical circle reading

A $(1 - k/2)/R = 1.47 * 10^{-7} [m^{-1}]$

B $(1 - k)/2R = 6.83 * 10^{-8} [m^{-1}]$

k 0.13 (mean refraction coefficient)

R $6.378 * 10^6$ m (radius of the earth)

Earth curvature (1/R) and mean refraction coefficient (k) are automatically taken into account when calculating the horizontal distance and height difference. The calculated horizontal distance relates to the station height and not to the reflector height.

Distance measuring program Averaging

In the distance measuring program Averaging, the following values are displayed:

D Slope distance as arithmetic mean of all measurements

s Standard deviation of a single measurement

n Number of measurements

These values are calculated as follows:

$$\bar{D} = \frac{1}{n} \cdot \sum_{i=1}^n D_i$$

TS.114

$$s = \sqrt{\frac{\sum_{i=1}^n (D_i - \bar{D})^2}{n - 1}} = \sqrt{\frac{\sum_{i=1}^n D_i^2 - \frac{1}{n} \left(\sum_{i=1}^n D_i \right)^2}{n - 1}}$$

TS.115

\bar{D} Slope distance as arithmetic mean of all measurements

Σ Sum

D_i Single slope distance measurement

n Number of measurements

s Standard deviation of a single slope distance measurement

Σ Sum

\bar{D} Slope distance as arithmetic mean of all measurements

D_i Single slope distance measurement

n Number of distance measurements

The standard deviation $s_{\bar{D}}$ of the arithmetic mean of the distance can be calculated as follows:

$$s_{\bar{D}} = \frac{s}{\sqrt{n}}$$

TS.116

$s_{\bar{D}}$ Standard deviation of the arithmetic mean of the distance

s Standard deviation of a single measurement

n Number of measurements

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- when it has to be **right**

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